

Multidimensional Disjunctive Inequalities for Linear Chance-Constrained Problems with Finite Support

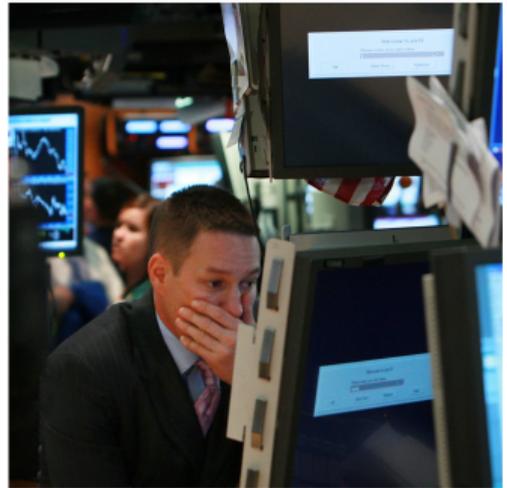
AIROYoung Workshop

Diego Cattaruzza, Martine Labbé, Matteo Petris, Marius Roland, Martin Schmidt

Université Libre de Bruxelles, Belgium

February 10-13, 2026

How much attention do extreme events deserve?



Chance Constrained Stochastic Programs (CCSPs)

$$\begin{aligned} v^* &= \min_{x \in \mathcal{X}} f(x) \\ &\text{s.t.} \quad x \in X(\xi) \end{aligned}$$

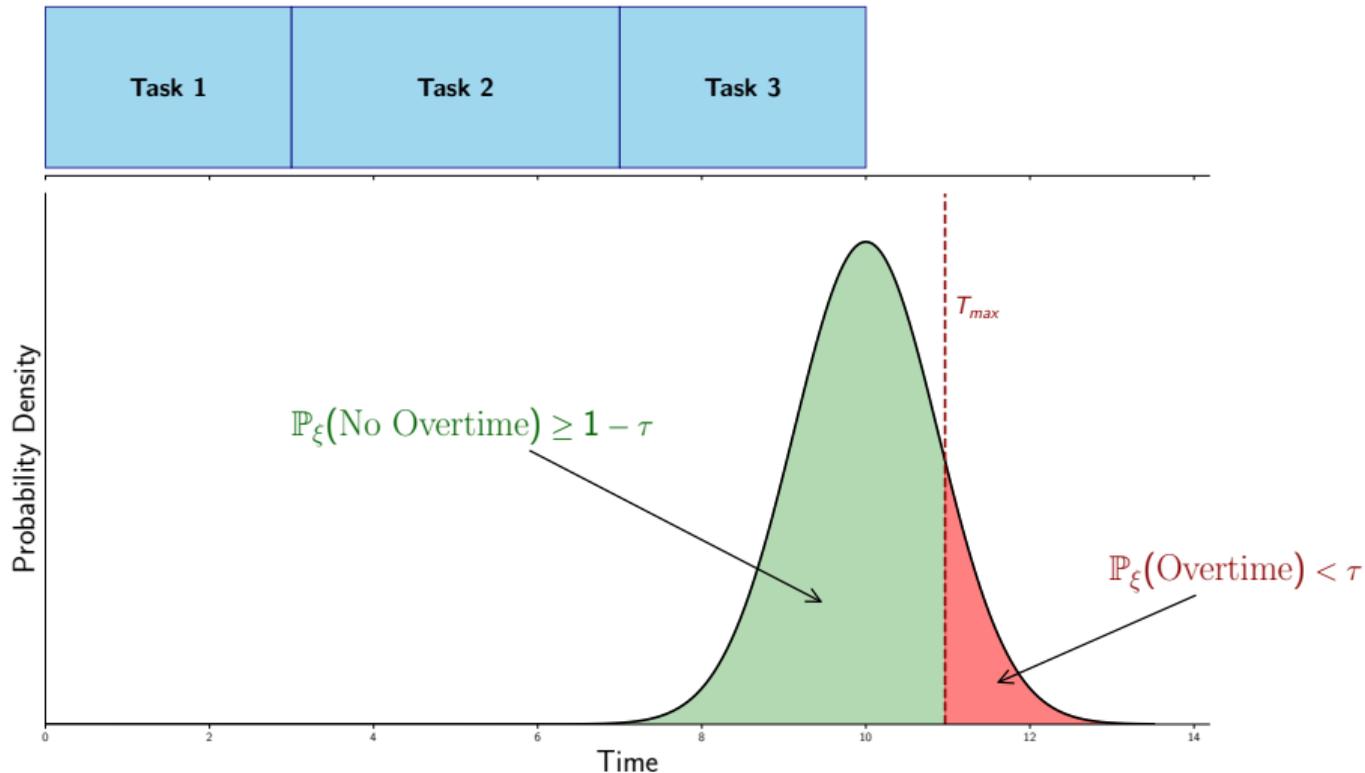
Chance Constrained Stochastic Programs (CCSPs)

$$\begin{aligned} v^* &= \min_{x \in \mathcal{X}} f(x) \\ &\text{s.t. } \mathbb{P}_\xi[x \in X(\xi)] = 1 \end{aligned}$$

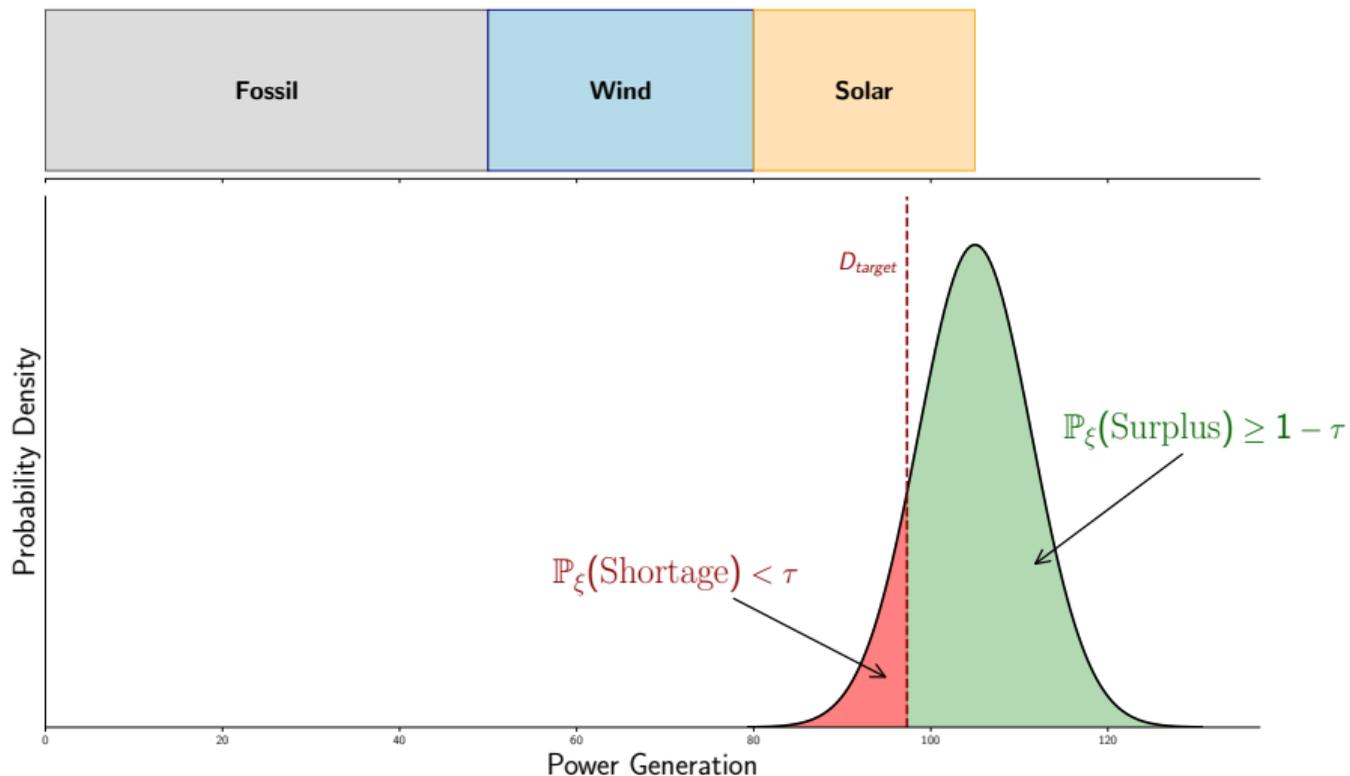
Chance Constrained Stochastic Programs (CCSPs)

$$\begin{aligned} v^* &= \min_{x \in \mathcal{X}} f(x) \\ &\text{s.t. } \mathbb{P}_{\xi}[x \in X(\xi)] \geq 1 - \tau \end{aligned}$$

Applications: Scheduling with Uncertain Durations



Applications: Energy Demand Satisfaction



Overview

1. Introduction
2. Setting and Challenges
3. State of the Art
4. Multi Dimensional Disjunctive Inequalities
5. Numerical Experiments
6. Conclusion

Setting and Challenges

CCSP with Finite Support

Assume

$$\xi \in \{\xi^s \in \mathbb{R}^d : s \in S\}$$

CCSP with Finite Support

Assume

$$\xi \in \{\xi^s \in \mathbb{R}^d : s \in S\}$$

Parameters & Variables

$$p_s \in [0, 1], X^s = X(\xi^s)$$

$$z_s \in \{0, 1\}$$

CCSP with Finite Support

Assume

$$\xi \in \{\xi^s \in \mathbb{R}^d : s \in S\}$$

Parameters & Variables

$$p_s \in [0, 1], X^s = X(\xi^s)$$

$$z_s \in \{0, 1\}$$

Model

$$v^* = \min_{x \in \mathcal{X}} f(x)$$

$$\text{s.t. } \mathbb{P}_\xi[x \in X(\xi)] \geq 1 - \tau$$

→

$$v^* = \min_{x \in \mathcal{X}} f(x)$$

$$\text{s.t. } z_s = \mathbb{1}(x \in X^s), \quad s \in S$$

$$\sum_{s \in S} p_s z_s \geq 1 - \tau$$

$$z_s \in \{0, 1\}, \quad s \in S$$

CCSP with Finite Support

Assume

$$\xi \in \{\xi^s \in \mathbb{R}^d : s \in S\}$$

Parameters & Variables

$$p_s \in [0, 1], X^s = X(\xi^s)$$

$$z_s \in \{0, 1\}$$

Model

$$v^* = \min_{x \in \mathcal{X}} f(x)$$

→

$$v^* = \min_{x \in \mathcal{X}} f(x)$$

$$\text{s.t. } \mathbb{P}_\xi[x \in X(\xi)] \geq 1 - \tau$$

$$\text{s.t. } z_s = \mathbb{1}(x \in X^s), \quad s \in S$$

$$\sum_{s \in S} p_s z_s \geq 1 - \tau$$

$$z_s \in \{0, 1\}, \quad s \in S$$

CCSP with Finite Support

Assume

$$\xi \in \{\xi^s \in \mathbb{R}^d : s \in S\}$$

Parameters & Variables

$$p_s \in [0, 1], X^s = X(\xi^s)$$

$$z_s \in \{0, 1\}$$

Model

$$v^* = \min_{x \in \mathcal{X}} f(x)$$

$$\text{s.t. } \mathbb{P}_\xi[x \in X(\xi)] \geq 1 - \tau$$

→

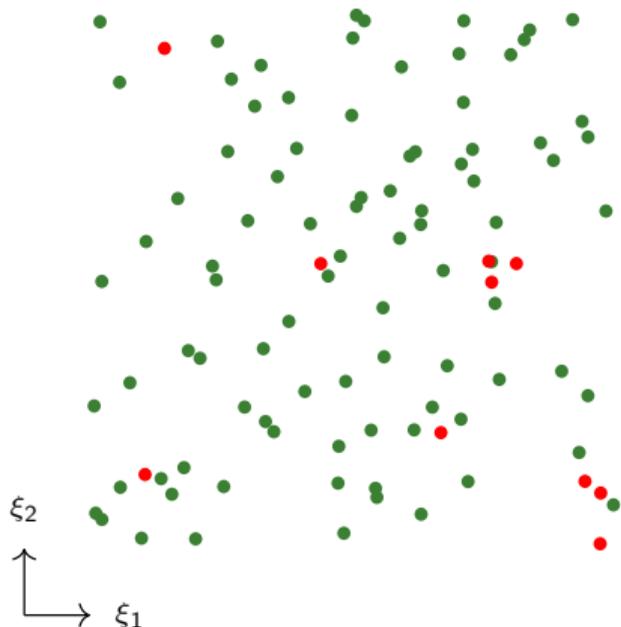
$$v^* = \min_{x \in \mathcal{X}} f(x)$$

$$\text{s.t. } z_s = \mathbb{1}(x \in X^s), \quad s \in S$$

$$\sum_{s \in S} p_s z_s \geq 1 - \tau$$

$$z_s \in \{0, 1\}, \quad s \in S$$

Feasibility with Finite Support



For \underline{x} , assume $\exists \blacksquare, \blacksquare \subseteq \mathcal{E}$,

$$\underline{x} \in X(\xi), \forall \xi \in \blacksquare$$

and

$$\underline{x} \notin X(\xi), \forall \xi \in \blacksquare$$

Then, \underline{x} is feasible if

$$\mathbb{P}(\xi \in \blacksquare) \geq 1 - \tau$$

or equivalently

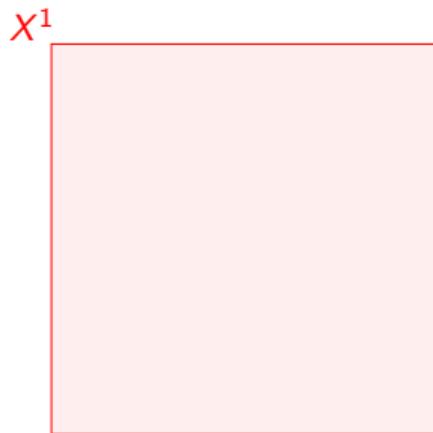
$$\mathbb{P}(\xi \in \blacksquare) \leq \tau$$

Challenge 1: Nonconvexity & Nonsmoothness

$$\begin{aligned} \min_{x \in \mathbb{R}^n} \quad & f(x) \\ \text{s.t.} \quad & z_s = \mathbb{1}(x \in X^s), \quad s \in \{1, 2, 3\} \\ & \sum_{s \in \{1, 2, 3\}} p_s z_s \geq 1 - \tau \\ & z_s \in \{0, 1\} \end{aligned}$$

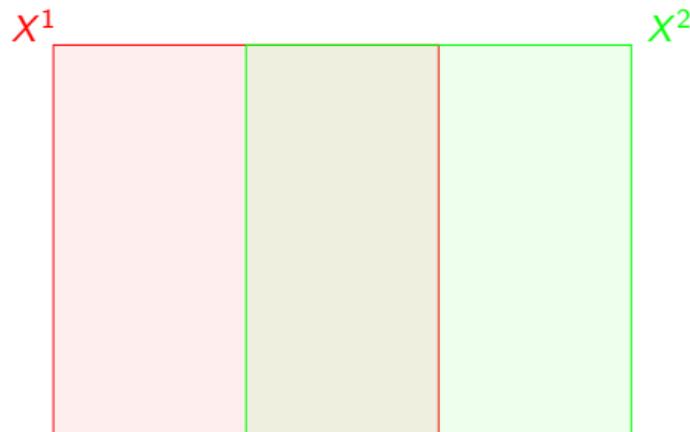
Challenge 1: Nonconvexity & Nonsmoothness

$$\begin{aligned} \min_{x \in \mathbb{R}^n} \quad & f(x) \\ \text{s.t.} \quad & z_s = \mathbb{1}(x \in X^s), \quad s \in \{1, 2, 3\} \\ & \sum_{s \in \{1, 2, 3\}} p_s z_s \geq 1 - \tau \\ & z_s \in \{0, 1\} \end{aligned}$$



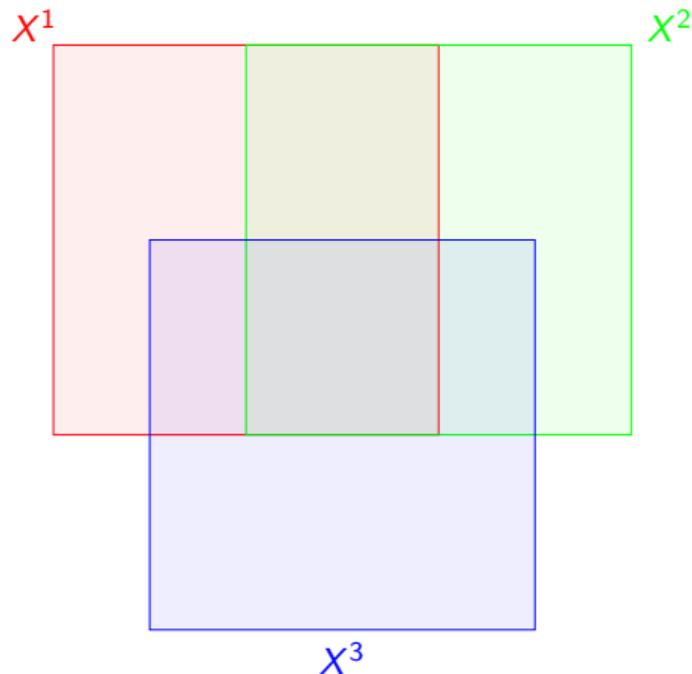
Challenge 1: Nonconvexity & Nonsmoothness

$$\begin{aligned} \min_{x \in \mathbb{R}^n} \quad & f(x) \\ \text{s.t.} \quad & z_s = \mathbb{1}(x \in X^s), \quad s \in \{1, 2, 3\} \\ & \sum_{s \in \{1, 2, 3\}} p_s z_s \geq 1 - \tau \\ & z_s \in \{0, 1\} \end{aligned}$$



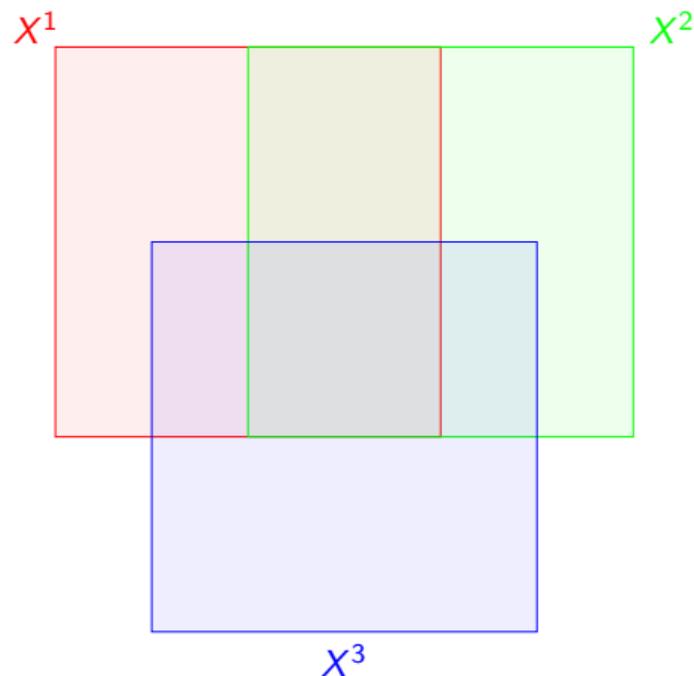
Challenge 1: Nonconvexity & Nonsmoothness

$$\begin{aligned} \min_{x \in \mathbb{R}^n} \quad & f(x) \\ \text{s.t.} \quad & z_s = \mathbb{1}(x \in X^s), \quad s \in \{1, 2, 3\} \\ & \sum_{s \in \{1, 2, 3\}} p_s z_s \geq 1 - \tau \\ & z_s \in \{0, 1\} \end{aligned}$$



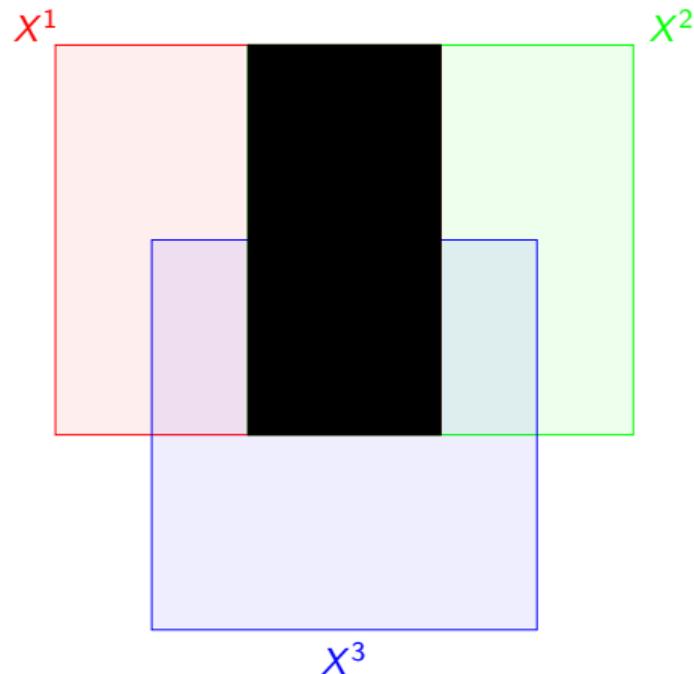
Challenge 1: Nonconvexity & Nonsmoothness

$$\begin{aligned} \min_{x \in \mathbb{R}^n} \quad & f(x) \\ \text{s.t.} \quad & z_s = \mathbb{1}(x \in X^s), \quad s \in \{1, 2, 3\} \\ & \sum_{s \in \{1, 2, 3\}} z_s \geq 2 \\ & z_s \in \{0, 1\} \end{aligned}$$



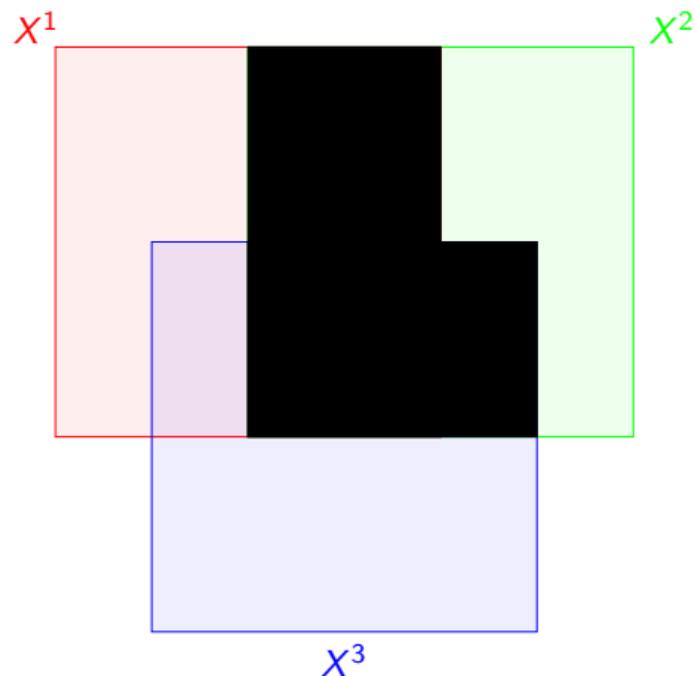
Challenge 1: Nonconvexity & Nonsmoothness

$$\begin{aligned} \min_{x \in \mathbb{R}^n} \quad & f(x) \\ \text{s.t.} \quad & z_s = \mathbb{1}(x \in X^s), \quad s \in \{1, 2, 3\} \\ & \sum_{s \in \{1, 2, 3\}} z_s \geq 2 \\ & z_s \in \{0, 1\} \end{aligned}$$



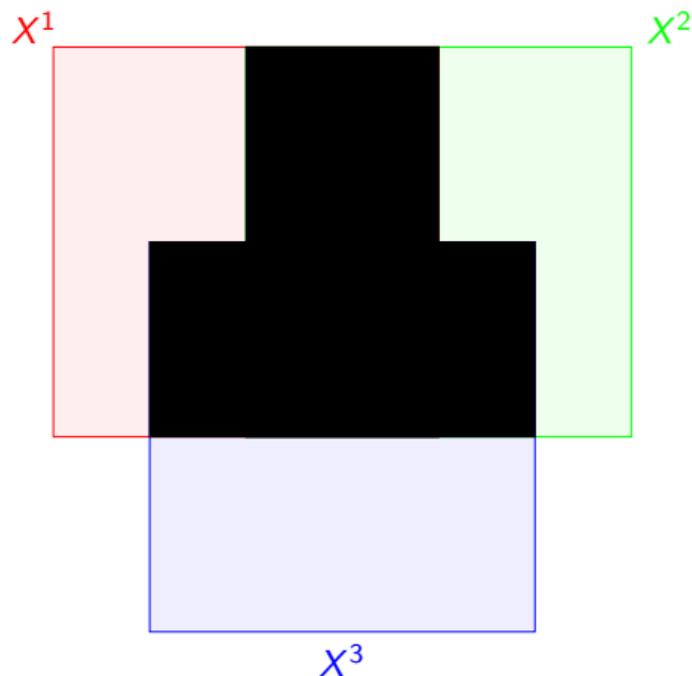
Challenge 1: Nonconvexity & Nonsmoothness

$$\begin{aligned} \min_{x \in \mathbb{R}^n} \quad & f(x) \\ \text{s.t.} \quad & z_s = \mathbb{1}(x \in X^s), \quad s \in \{1, 2, 3\} \\ & \sum_{s \in \{1, 2, 3\}} z_s \geq 2 \\ & z_s \in \{0, 1\} \end{aligned}$$



Challenge 1: Nonconvexity & Nonsmoothness

$$\begin{aligned} \min_{x \in \mathbb{R}^n} \quad & f(x) \\ \text{s.t.} \quad & z_s = \mathbb{1}(x \in X^s), \quad s \in \{1, 2, 3\} \\ & \sum_{s \in \{1, 2, 3\}} z_s \geq 2 \\ & z_s \in \{0, 1\} \end{aligned}$$



Challenge 1: Nonconvexity & Nonsmoothness

$$\begin{aligned} \min_{x \in \mathbb{R}^n} \quad & f(x) \\ \text{s.t.} \quad & z_s = \mathbb{1}(x \in X^s), \quad s \in \{1, 2, 3\} \\ & \sum_{s \in \{1, 2, 3\}} z_s \geq 2 \\ & z_s \in \{0, 1\} \end{aligned}$$



Challenge 1: Nonconvexity & Nonsmoothness

$$\begin{aligned} \min_{x \in \mathbb{R}^n} \quad & f(x) \\ \text{s.t.} \quad & z_s = \mathbb{1}(x \in X^s), \quad s \in \{1, 2, 3\} \\ & \sum_{s \in \{1, 2, 3\}} z_s \geq 2 \\ & z_s \in \{0, 1\} \end{aligned}$$



→ Nonconvex nonsmooth x -space and $\binom{|S|}{\tau |S|}$ operations

Challenge 1: Nonconvexity & Nonsmoothness

$$\begin{aligned} \min_{x \in \mathbb{R}^n} \quad & f(x) \\ \text{s.t.} \quad & z_s = \mathbb{1}(x \in X^s), \quad s \in \{1, 2, 3\} \\ & \sum_{s \in \{1, 2, 3\}} z_s \geq 2 \\ & z_s \in \{0, 1\} \end{aligned}$$



- Nonconvex nonsmooth x -space and $\binom{|S|}{\lfloor \tau |S| \rfloor}$ operations
- NP-hard to solve even for simplified cases (Luedtke et al. 2010)

Linear CCSP with Equiprobable Scenarios

Assumptions

$$p_s = \frac{1}{|S|}$$

$$X^s = \{x \in \mathbb{R}^n : A^s x \geq b^s\}$$

$$f(x) = c^\top x$$

Linear CCSP with Equiprobable Scenarios

Assumptions

$$p_s = \frac{1}{|S|}$$

$$X^s = \{x \in \mathbb{R}^n : A^s x \geq b^s\}$$

$$f(x) = c^T x$$

Model

$$v^* = \min_{x \in \mathcal{X}} f(x)$$

$$\text{s.t. } z_s = \mathbb{1}(x \in X^s), \quad s \in S$$

$$\sum_{s \in S} p_s z_s \geq 1 - \tau$$

$$z_s \in \{0, 1\}, \quad s \in S$$

$$\rightarrow v^* = \min_{x \in \mathcal{X}} c^T x$$

$$\text{s.t. } z_s = \mathbb{1}(A^s x \geq b^s), \quad s \in S$$

$$\sum_{s \in S} z_s \geq |S| - \tau |S|$$

$$z_s \in \{0, 1\}, \quad s \in S$$

Linear CCSP with Equiprobable Scenarios

Assumptions

$$p_s = \frac{1}{|S|}$$

$$X^s = \{x \in \mathbb{R}^n : A^s x \geq b^s\}$$

$$f(x) = c^T x$$

Model

$$v^* = \min_{x \in \mathcal{X}} f(x)$$

$$\text{s.t. } z_s = \mathbb{1}(x \in X^s), \quad s \in S$$

$$\sum_{s \in S} p_s z_s \geq 1 - \tau$$

$$z_s \in \{0, 1\}, \quad s \in S$$

$$\rightarrow v^* = \min_{x \in \mathcal{X}} c^T x$$

$$\text{s.t. } z_s = \mathbb{1}(A^s x \geq b^s), \quad s \in S$$

$$\sum_{s \in S} z_s \geq |S| - \tau |S|$$

$$z_s \in \{0, 1\}, \quad s \in S$$

Linear CCSP with Equiprobable Scenarios

Assumptions

$$p_s = \frac{1}{|S|}$$

$$X^s = \{x \in \mathbb{R}^n : A^s x \geq b^s\}$$

$$f(x) = c^T x$$

Model

$$v^* = \min_{x \in \mathcal{X}} f(x)$$

$$\text{s.t. } z_s = \mathbb{1}(x \in X^s), \quad s \in S$$

$$\sum_{s \in S} p_s z_s \geq 1 - \tau$$

$$z_s \in \{0, 1\}, \quad s \in S$$

$$\rightarrow v^* = \min_{x \in \mathcal{X}} c^T x$$

$$\text{s.t. } z_s = \mathbb{1}(A^s x \geq b^s), \quad s \in S$$

$$\sum_{s \in S} z_s \geq |S| - \tau |S|$$

$$z_s \in \{0, 1\}, \quad s \in S$$

Linear CCSP with Equiprobable Scenarios

Assumptions

$$p_s = \frac{1}{|S|}$$

$$X^s = \{x \in \mathbb{R}^n : A^s x \geq b^s\}$$

$$f(x) = c^T x$$

Model

$$v^* = \min_{x \in \mathcal{X}} f(x)$$

$$\text{s.t. } z_s = \mathbb{1}(x \in X^s), \quad s \in S$$

$$\sum_{s \in S} p_s z_s \geq 1 - \tau$$

$$z_s \in \{0, 1\}, \quad s \in S$$

$$\rightarrow v^* = \min_{x \in \mathcal{X}} c^T x$$

$$\text{s.t. } z_s = \mathbb{1}(A^s x \geq b^s), \quad s \in S$$

$$\sum_{s \in S} z_s \geq |S| - \lfloor \tau |S| \rfloor$$

$$z_s \in \{0, 1\}, \quad s \in S$$

Linear CCSP with Equiprobable Scenarios

Assumptions

$$p_s = \frac{1}{|S|}$$

$$X^s = \{x \in \mathbb{R}^n : A^s x \geq b^s\}$$

$$f(x) = c^T x$$

Model

$$v^* = \min_{x \in \mathcal{X}} f(x)$$

$$\text{s.t. } z_s = \mathbb{1}(x \in X^s), \quad s \in S$$

$$\sum_{s \in S} p_s z_s \geq 1 - \tau$$

$$z_s \in \{0, 1\}, \quad s \in S$$

$$\rightarrow v^* = \min_{x \in \mathcal{X}} c^T x$$

$$\text{s.t. } z_s = \mathbb{1}(A^s x \geq b^s), \quad s \in S$$

$$\sum_{s \in S} z_s \geq |S| - \lfloor \tau |S| \rfloor$$

$$z_s \in \{0, 1\}, \quad s \in S$$

Big-M Coefficients: Reformulation

Reformulation

$$z_s = \mathbb{1}(A^s x \geq b^s) \quad \rightarrow \quad A^s x - b^s \geq M(1 - z_s)$$

Model

$$\begin{aligned} v^* = \min_{x \in \mathcal{X}} \quad & c^\top x \\ \text{s.t.} \quad & A^s x - b^s \geq M(1 - z_s), \quad s \in S \\ & \sum_{s \in S} z_s \geq |S| - \lfloor \tau |S| \rfloor \\ & z_s \in \{0, 1\}, \quad s \in S \end{aligned}$$

Challenge 2: Relaxation Strength

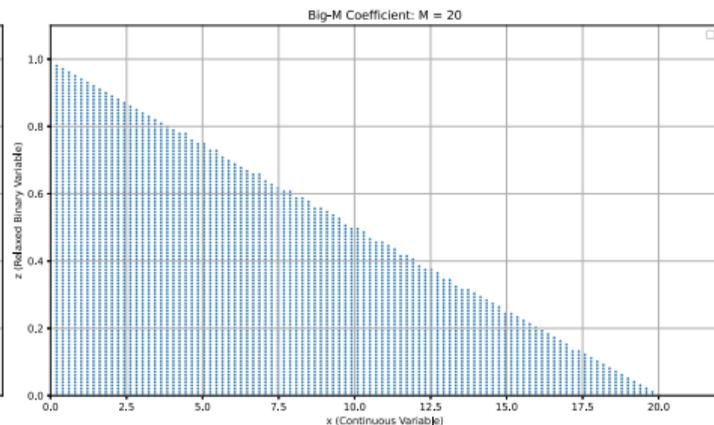
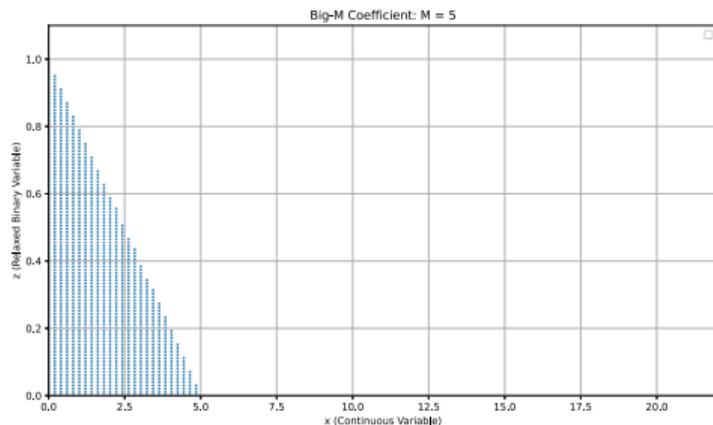
Example

$$z = \mathbb{1}(x \leq 0)$$



$$x \leq M(1 - z)$$

Illustration



State of the Art

Overview: Strengthening Techniques

Cutting planes

Mixing-Set (Luedtke 2014; Song et al. 2014), Quantile (Xie et al. 2018), Infeasible Irreducible Subsystems (Tanner et al. 2010), Multi-Disjunctive (Cattaruzza et al. 2024)

Big-M tightening

Instance-Specific (Song et al. 2014), Generic (Qiu et al. 2014)

Convex Approximations

Outer (Ahmed et al. 2017), Inner (Jiang et al. 2022; Nemirovski et al. 2007)

Alternative Approaches

Adaptive Partitioning (Roland et al. 2023)

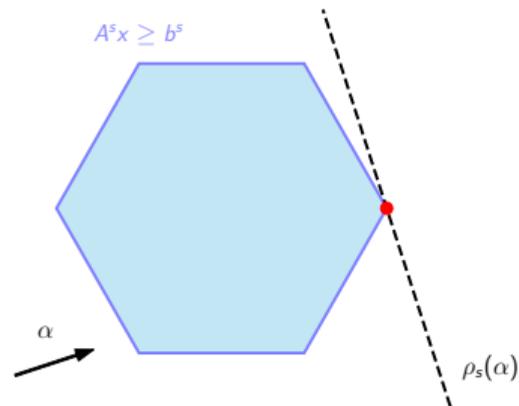
The Quantile Bound I

The Quantile Bound I

Single Scenario Cost

$$\rho_s(\alpha) := \min \alpha^\top x$$

s.t. $A^s x \geq b^s$



The Quantile Bound I

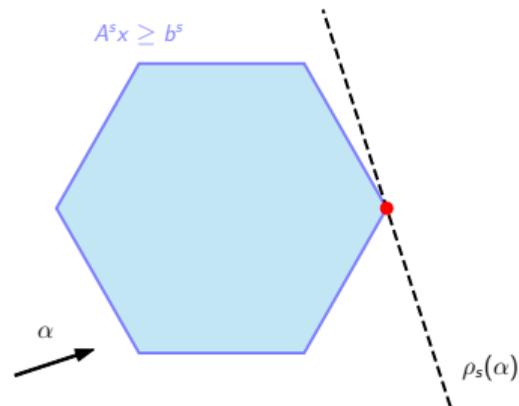
Single Scenario Cost

$$\rho_s(\alpha) := \min \alpha^\top x$$

s.t. $A^s x \geq b^s$

Property

$$\text{If } z_s = 1 \quad \rightarrow \quad \alpha^\top x \geq \rho_s(\alpha)$$



The Quantile Bound I

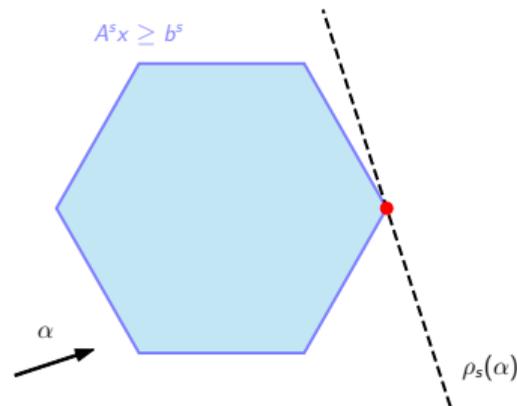
Single Scenario Cost

$$\rho_s(\alpha) := \min_{x} \alpha^\top x$$

s.t. $A^s x \geq b^s$

Property

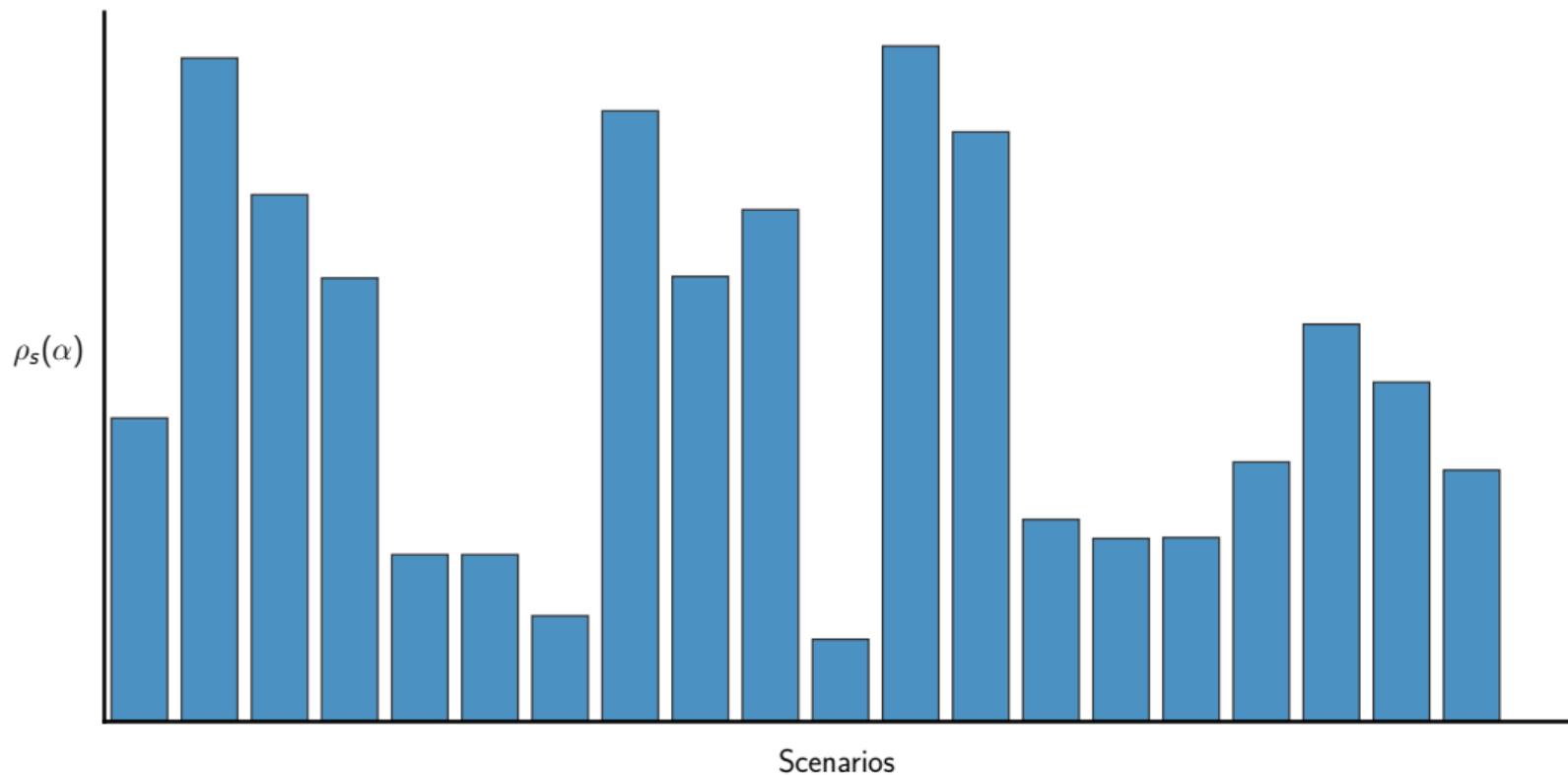
$$\text{If } z_s = 1 \quad \rightarrow \quad \alpha^\top x \geq \rho_s(\alpha)$$



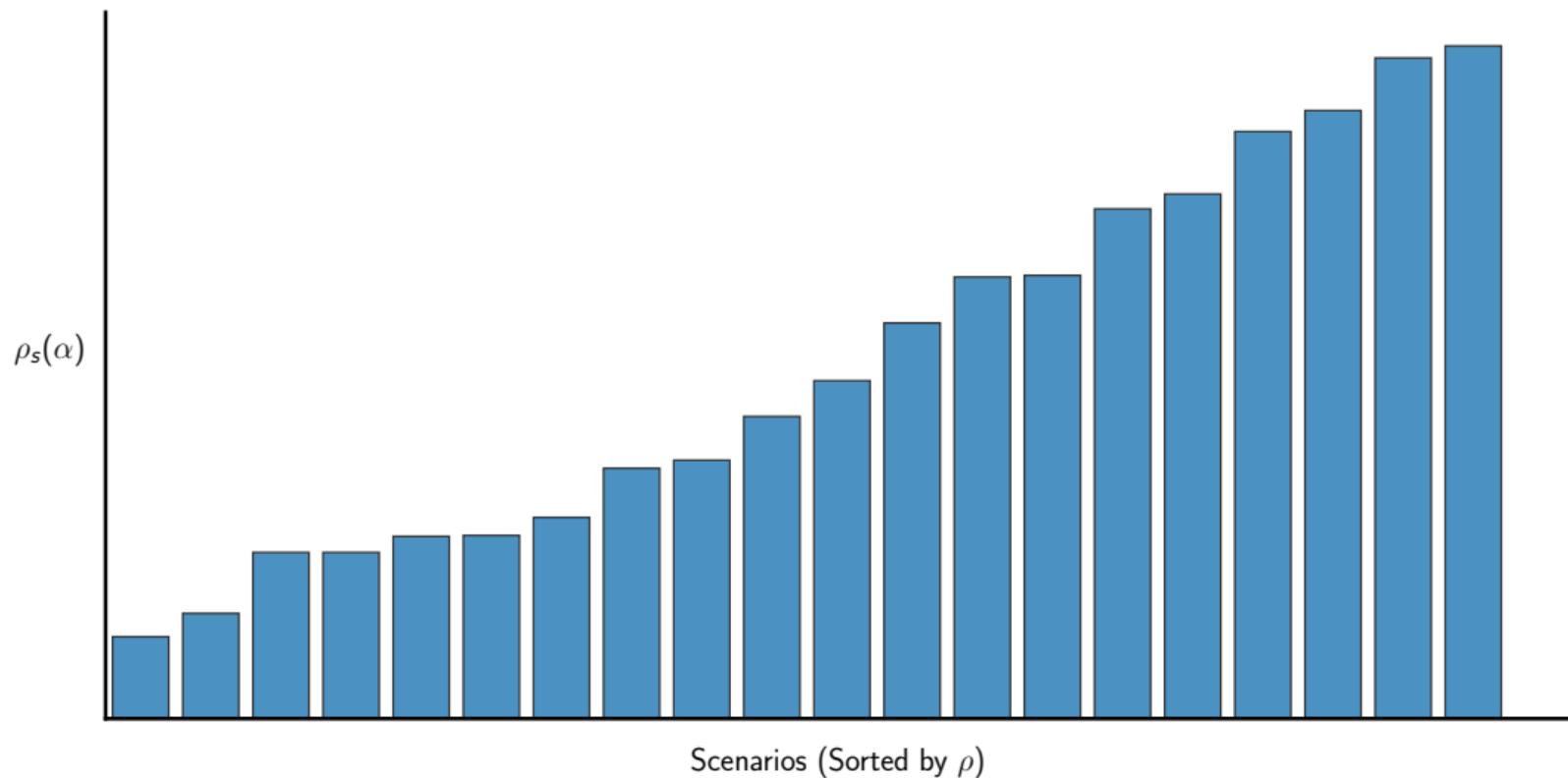
Generalization

$$\alpha^\top x \geq \max_{s \in S} \{\rho_s(\alpha) : z_s = 1\}$$

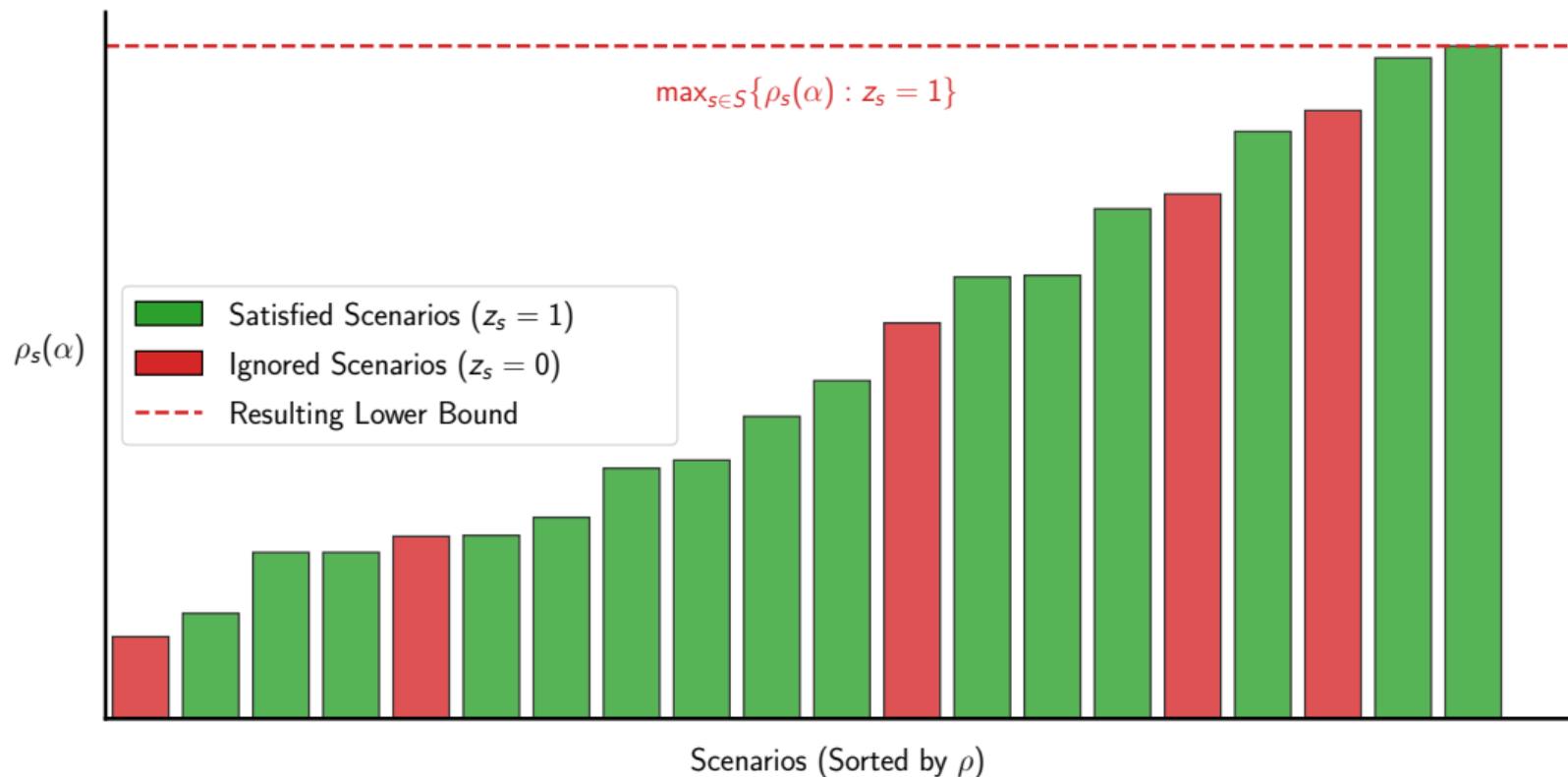
The Quantile Bound II



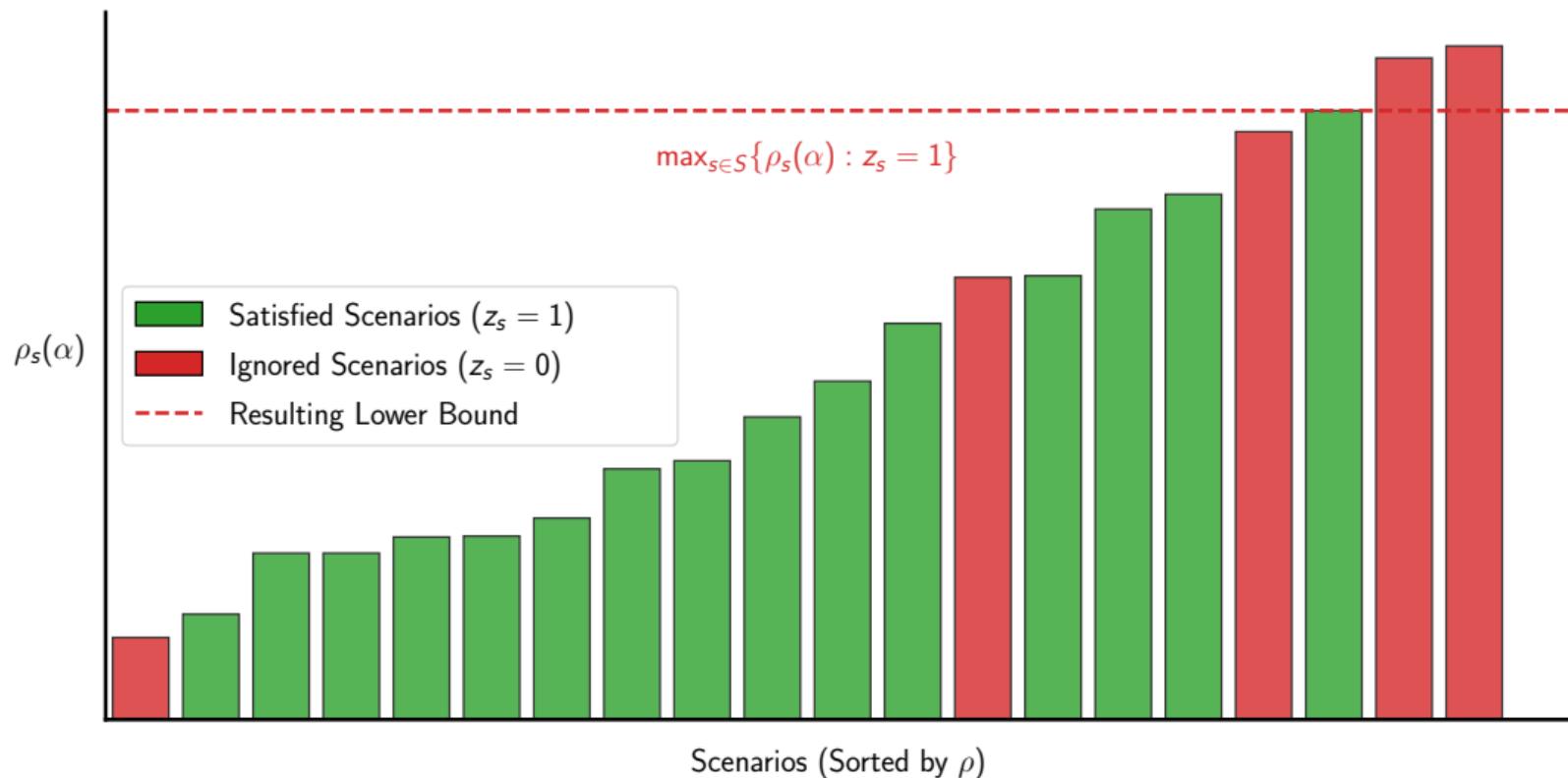
The Quantile Bound II



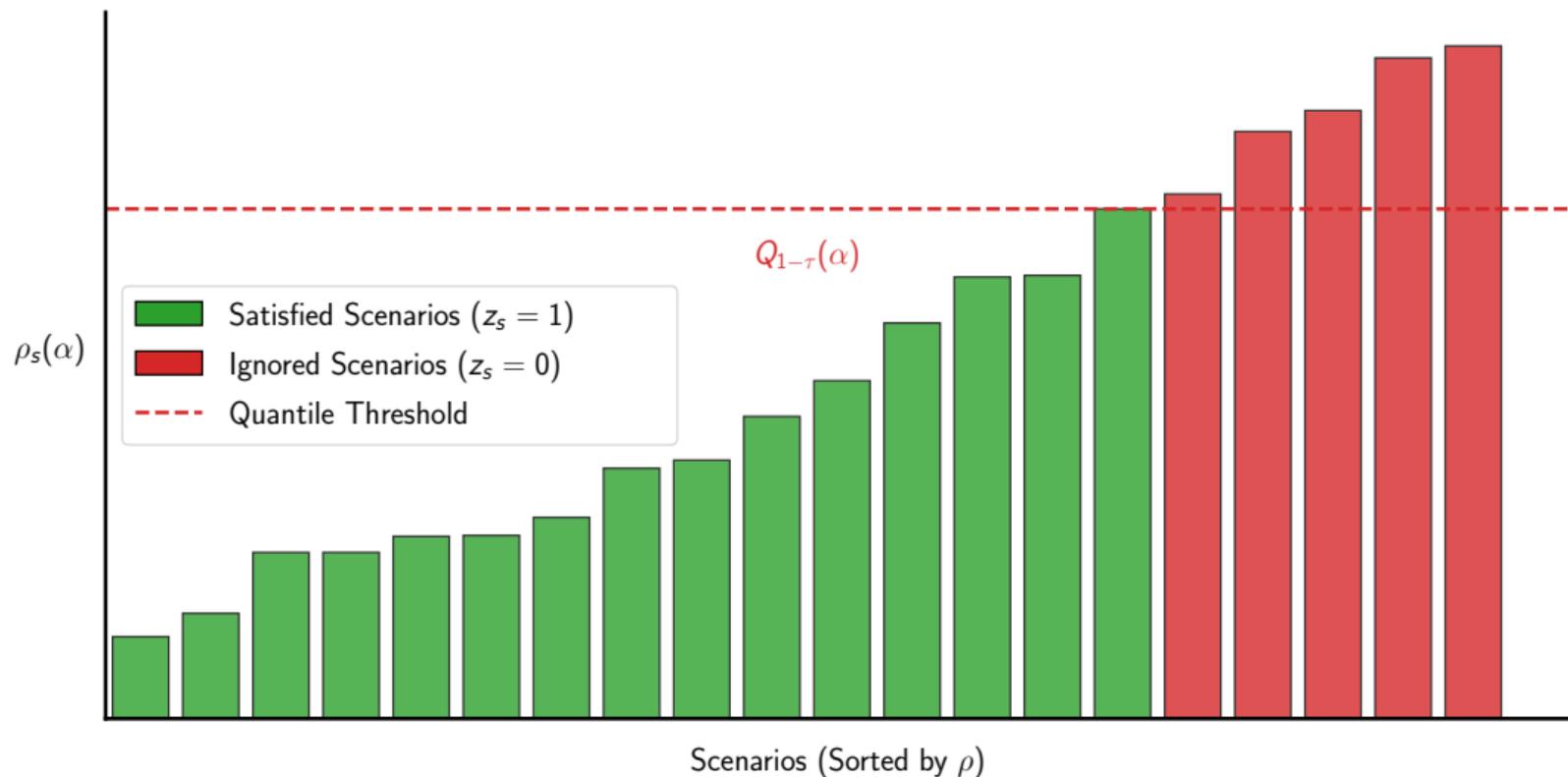
The Quantile Bound II



The Quantile Bound II



The Quantile Bound II



Quantile Inequality

1. Select $\alpha \in \mathbb{R}^n$

Quantile Inequality

1. Select $\alpha \in \mathbb{R}^n$
2. Compute $\rho_s(\alpha)$ for all $s \in S$

Quantile Inequality

1. Select $\alpha \in \mathbb{R}^n$
2. Compute $\rho_s(\alpha)$ for all $s \in S$
3. Sort $\phi : S \rightarrow S$ such that

$$\rho_{\phi_1}(\alpha) \leq \rho_{\phi_2}(\alpha) \leq \cdots \leq \rho_{\phi_{|S|}}(\alpha)$$

Quantile Inequality

1. Select $\alpha \in \mathbb{R}^n$
2. Compute $\rho_s(\alpha)$ for all $s \in S$
3. Sort $\phi : S \rightarrow S$ such that

$$\rho_{\phi_1}(\alpha) \leq \rho_{\phi_2}(\alpha) \leq \cdots \leq \rho_{\phi_{|S|}}(\alpha)$$

4. Valid Inequality

$$\alpha^\top x \geq \max_{s \in S} \{\rho_s(\alpha) : z_s = 1\}$$

Quantile Inequality

1. Select $\alpha \in \mathbb{R}^n$
2. Compute $\rho_s(\alpha)$ for all $s \in S$
3. Sort $\phi : S \rightarrow S$ such that

$$\rho_{\phi_1}(\alpha) \leq \rho_{\phi_2}(\alpha) \leq \cdots \leq \rho_{\phi_{|S|}}(\alpha)$$

4. Valid Inequality

$$\alpha^\top x \geq \max_{s \in S} \{\rho_s(\alpha) : z_s = 1\} \geq Q(\alpha) := \rho_{\phi_{|S| - \lfloor \tau |S| \rfloor}}(\alpha)$$

Quantile Inequalities: Exact Separation

- How to choose α ?

→ Separation (finding the best α) in NP (Xie et al. 2018)

Quantile Inequalities: Heuristic Separation

- Computing Q → Select $\alpha + |S|$ LPs + argsort

→ Heuristics are expensive ...

→ Litterature: bounding $\rho_s(\alpha)$ (Song et al. 2014)

Strengthened Mixing Set

Observation: We can model the on-off relationship between x and z

Strengthened Mixing Set

Observation: We can model the on-off relationship between x and z

$$M(\alpha) = \left\{ (x, z) : \alpha^\top x \geq Q(\alpha) - (Q(\alpha) - \rho_s(\alpha))z_s, \forall s \text{ above } Q(\alpha) \right\}$$

Strengthened Mixing Set

Observation: We can model the on-off relationship between x and z

$$M(\alpha) = \left\{ (x, z) : \alpha^\top x \geq Q(\alpha) - (Q(\alpha) - \rho_s(\alpha))z_s, \forall s \text{ above } Q(\alpha) \right\}$$

Cases

→ If $z_s = 0$:

$$\alpha^\top x \geq Q(\alpha)$$

→ If $z_s = 1$:

$$\alpha^\top x \geq \rho_s(\alpha)$$

Mixing Sets: Closure

Mixing Sets: Closure

For $\alpha \in \mathbb{R}^n$ (Qiu et al. 2014)

$$\text{Proj}_x(\text{conv}(M(\alpha))) = \{x \in \mathbb{R}_+^n : \alpha^\top x \geq Q(\alpha)\}$$

Mixing Sets: Closure

For $\alpha \in \mathbb{R}^n$ (Qiu et al. 2014)

$$\text{Proj}_x(\text{conv}(M(\alpha))) = \{x \in \mathbb{R}_+^n : \alpha^\top x \geq Q(\alpha)\}$$

Basic Mixing Closure

$$\mathcal{BM} := \bigcap_{\alpha \in \mathbb{R}^n} \text{Proj}_x(\text{conv}(M(\alpha))) = \bigcap_{\alpha \in \mathbb{R}^n} \{x \in \mathbb{R}_+^n : \alpha^\top x \geq Q(\alpha)\} =: \mathcal{Q}$$

Mixing Sets: Closure

For $\alpha \in \mathbb{R}^n$ (Qiu et al. 2014)

$$\text{Proj}_x(\text{conv}(M(\alpha))) = \{x \in \mathbb{R}_+^n : \alpha^\top x \geq Q(\alpha)\}$$

Basic Mixing Closure

$$\mathcal{BM} := \bigcap_{\alpha \in \mathbb{R}^n} \text{Proj}_x(\text{conv}(M(\alpha))) = \bigcap_{\alpha \in \mathbb{R}^n} \{x \in \mathbb{R}_+^n : \alpha^\top x \geq Q(\alpha)\} =: \mathcal{Q}$$

→ What about the Real Mixing Closure?

$$\mathcal{M} := \text{Proj}_x \left(\bigcap_{\alpha \in \mathbb{R}^n} \text{conv}(M(\alpha)) \right) \quad \mathcal{M} \subseteq \mathcal{BM} = \mathcal{Q}$$

Mixing Sets: Exact Separation

- How to choose α ?

- Recall: $\mathcal{BM} = \mathcal{Q}$

→ As hard to separate as Q-inequalities

Mixing Sets: Heuristic Separation

- Computing $\rho_s(\alpha), Q(\alpha)$ \rightarrow Select $\alpha + |S|$ LPs + argsort

\rightarrow Heuristics are expensive ...

\rightarrow Litterature: bounding $\rho_s(\alpha)$ (Song et al. 2014)

Observation

- We consider the $Q(\alpha)$ scenario, but all other scenarios are ignored

- We haven't used the constraints $A^s x \geq b^s$

Multi Dimensional Disjunctive Inequalities

Disjunctive Aspect of CCSPs

Simple Example

$$S = \{A, B, C, D, E\}$$

$$\tau = 0.4 \rightarrow \lfloor \tau |S| \rfloor = 2$$

$$|\bar{S}| = 4$$

Property

→ At least $|\bar{S}| - \lfloor \tau |S| \rfloor$ scenarios inside \bar{S} are satisfied.

Remainder

$$|\hat{S}(\bar{x})| \geq |\bar{S}| - \lfloor \tau |S| \rfloor$$

Temporary Assumption

$$A^s x \geq b^s \quad \rightarrow \quad a^s x \geq b^s$$

Multi Dimensional Inequalities: Local Validity

Arbitrary subset

$$\bar{S} \subseteq S \quad \text{where} \quad |\bar{S}| \geq \lfloor \tau |S| \rfloor + 1$$

Multi Dimensional Inequalities: Local Validity

Arbitrary subset

$$\bar{S} \subseteq S \quad \text{where} \quad |\bar{S}| \geq \lfloor \tau |S| \rfloor + 1$$

Existence

$$|\hat{S}(\bar{x})| \geq |\bar{S}| - \lfloor \tau |S| \rfloor$$

Multi Dimensional Inequalities: Local Validity

Arbitrary subset

$$\bar{S} \subseteq S \quad \text{where} \quad |\bar{S}| \geq \lfloor \tau |S| \rfloor + 1$$

Existence

$$|\hat{S}(\bar{x})| \geq |\bar{S}| - \lfloor \tau |S| \rfloor$$

Summation

$$\sum_{i \in [n]} \left(\sum_{s \in \hat{S}(\bar{x})} (a_i^s) \right) \bar{x}_i \geq \sum_{s \in \hat{S}(\bar{x})} (b^s)$$

Multi Dimensional Inequalities: Upper Bound II

Upper Bound

$$\sum_{s \in \hat{S}(\bar{x})} (a_i^s) \leq U_i(\bar{S}) = \max_w \sum_{s \in \bar{S}} a_i^s w^s$$

s.t.

$$\sum_{s \in \bar{S}} w^s = |\bar{S}| - \lfloor \tau |S| \rfloor$$
$$w^s \in [0, 1], \quad s \in \bar{S}$$

Multi Dimensional Inequalities: Upper Bound II

Upper Bound

$$\begin{aligned} \sum_{s \in \hat{S}(\bar{x})} (a_i^s) \leq U_i(\bar{S}) &= \max_w \sum_{s \in \bar{S}} a_i^s w^s \\ \text{s.t.} \quad \sum_{s \in \bar{S}} w^s &= |\bar{S}| - \lfloor \tau |S| \rfloor \\ w^s &\in [0, 1], \quad s \in \bar{S} \end{aligned}$$

Lower Bound

$$\begin{aligned} \sum_{s \in \hat{S}(\bar{x})} (b^s) \geq L_i(\bar{S}) &= \min_w \sum_{s \in \bar{S}} b^s w^s \\ \text{s.t.} \quad \sum_{s \in \bar{S}} w^s &= |\bar{S}| - \lfloor \tau |S| \rfloor \\ w^s &\in [0, 1], \quad s \in \bar{S} \end{aligned}$$

Multi Dimensional Inequalities: Generalization I

Arbitrary subset

$$\bar{S} \subseteq S \quad \text{where} \quad |\bar{S}| \geq \lfloor \tau |S| \rfloor + 1$$

Valid Inequality

$$\sum_{i \in [n]} U_i(\bar{S}) x_i \geq L(\bar{S})$$

Parameters

$$U_i(\bar{S}) = \max_w \sum_{s \in \bar{S}} a_i^s w^s$$

$$\text{s.t.} \quad \sum_{s \in \bar{S}} w^s = |\bar{S}| - \lfloor \tau |S| \rfloor$$

$$w^s \in [0, 1], \quad s \in \bar{S}$$

$$L(\bar{S}) = \min_w \sum_{s \in \bar{S}} b^s w^s$$

$$\text{s.t.} \quad \sum_{s \in \bar{S}} w^s = |\bar{S}| - \lfloor \tau |S| \rfloor$$

$$w^s \in [0, 1], \quad s \in \bar{S}$$

Multi Dimensional Inequalities: Generalization II

Remove Assumption

$$a^s x \geq b^s \quad \rightarrow \quad (\lambda^s)^\top A^s x \geq (\lambda^s)^\top b^s$$

Multi Dimensional Inequalities: Generalization II

Remove Assumption

$$a^s x \geq b^s \quad \rightarrow \quad (\lambda^s)^\top A^s x \geq (\lambda^s)^\top b^s$$

Theorem (Conforti et al. 2014)

Inequality $\mu x \geq \delta$ is valid \Leftrightarrow there exists $\lambda^s \in \mathbb{R}^n$ such that

$$(\lambda^s)^\top A = \mu \quad \text{and} \quad (\lambda^s)^\top b \geq \delta.$$

Multi Dimensional Inequalities: Summary

1. Multiplier λ^s

→ One valid inequality ($\lambda^s A^s x \geq \lambda^s b^s$) for every $s \in \bar{S}$

2. Subset \bar{S}

→ Globally valid upper and lower bound (U_i and L)

Multi Dimensional Inequalities: Closure

Multi Dimensional Closure

$$\mathcal{MD} := \bigcap_{\bar{s}, \lambda} \left\{ x \in \mathbb{R}_+^n : \sum_{i \in [n]} U_i(\lambda^s, \bar{s}) x_i \geq L(\lambda^s, \bar{s}) \right\}$$

Multi Dimensional Inequalities: Closure

Multi Dimensional Closure

$$\mathcal{MD} := \bigcap_{\bar{S}, \lambda} \left\{ x \in \mathbb{R}_+^n : \sum_{i \in [n]} U_i(\lambda^S, \bar{S}) x_i \geq L(\lambda^S, \bar{S}) \right\}$$

Proper Subset

$$\mathcal{MD} \subset \mathcal{Q} = \mathcal{BM}$$

→ (⊆) \mathcal{Q} special case where $|\bar{S}| = \lfloor \tau |S| \rfloor + 1$

→ (⊂) Can construct instances where inclusion is strict.

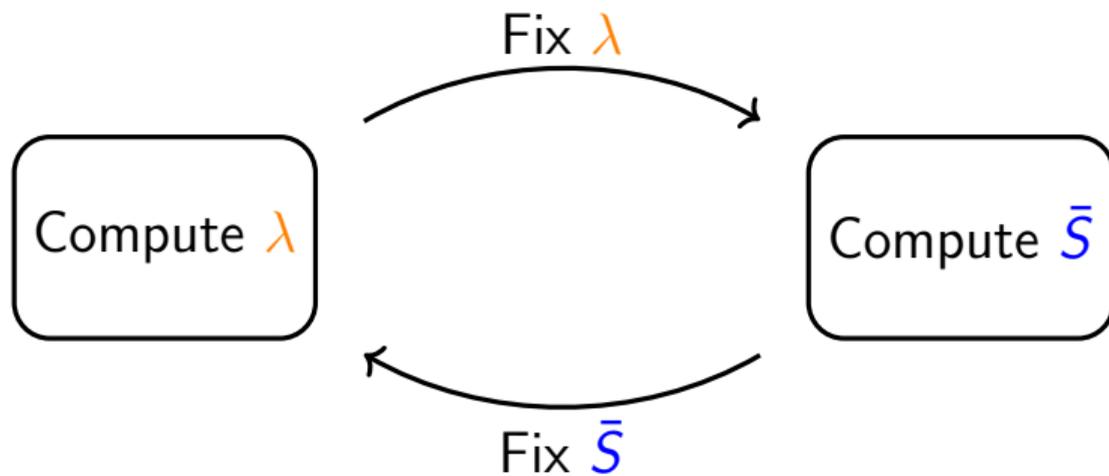
Multi Dimensional Inequalities: Exact Separation

- Separation in NP

→ Computing optimal λ^s in P (LP)

→ Computing good **heuristic** \bar{S} in P (Greedy Algorithm)

Separation Heuristic: ADM-Like



→ We carry out one iteration per direction

Separation Heuristics: Constraint-wise

1. One constraint j at a time

$$A^s x \geq b^s \quad \rightarrow \quad A_{j.}^s x \geq b_j^s$$

2. Compute \bar{s} for every j

3. Select most violated j

Numerical Experiments

Multidimensional Knapsack Instances: Generation

Base Instance



$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \leq \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$

Perturbation

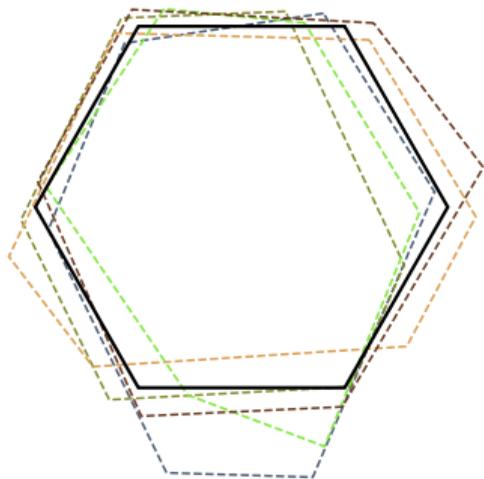
$$a_{ij}^s \sim \mathcal{N}(\mu = a_{ij}, \sigma^2 = 0.1 \cdot a_{ij})$$

Big-M (Naive)

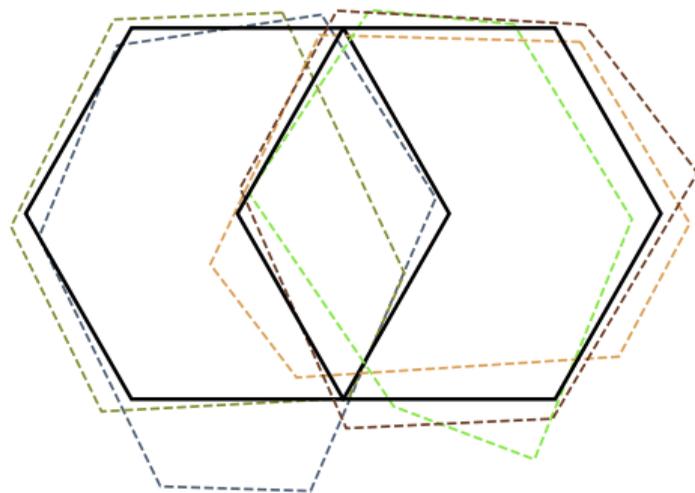
$$M_{j.}^s = A_{j.}^s \cdot 1$$

Multidimensional Knapsack Instances: Visualization

Litterature (Lit)



New (New)



Cutting Plane Method: Setup

- **Instances:** Perturbed Multidimensional Knapsack
 - **Software:** Python, Gurobi, Cython
 - **Benchmark:** Quantile and Mixing based on Song et al. 2014
- Choose α based on violated constraints
- Knapsack specific: tight lower bound on $\rho_s(\alpha)$

Cutting Plane Method: Results

Instances		MD-VIs													
		ADM					C-Wise			Mixing-set			Quantile		
(n, m)	Gen.	$ S $	$s(\lambda)$	T	it.	v (%)	T	it.	v (%)	T	it.	v (%)	T	it.	v (%)
mk-20-10	lit	100	0.87	0.18	18.80	30.21	0.46	4.00	28.05	0.11	4.80	25.07	0.11	4.20	21.18
		500	0.73	0.42	13.80	25.50	0.59	4.00	23.47	0.52	6.20	22.10	0.51	3.80	19.84
		1000	0.89	0.81	15.00	27.00	0.65	3.80	25.14	1.09	9.00	24.47	1.04	5.00	21.89
		3000	0.88	3.27	11.80	25.80	0.76	3.40	24.77	3.88	17.80	22.99	3.23	4.80	20.82
	new	100	0.33	0.23	21.60	24.03	0.63	3.60	4.30	0.12	5.20	16.30	0.12	2.40	0.92
		500	0.33	0.43	30.80	27.27	0.80	4.20	10.97	0.60	8.00	18.60	0.58	4.00	1.55
		1000	0.29	0.79	15.80	25.10	0.86	3.00	11.31	1.17	8.40	15.92	1.09	4.20	2.65
		3000	0.31	3.04	22.20	25.20	0.74	3.80	5.21	3.72	18.20	16.67	3.40	3.80	2.11
mk-40-30	lit	100	0.77	0.62	39.80	27.65	0.73	4.20	25.05	1.36	6.40	22.78	1.37	5.60	15.81
		500	0.79	1.27	21.00	26.13	0.61	3.80	23.66	6.72	7.40	19.72	6.67	4.60	16.04
		1000	0.73	3.17	47.40	28.19	0.76	4.20	25.46	13.55	12.40	22.74	11.83	6.20	18.94
		3000	0.79	8.96	20.80	25.59	0.78	3.60	23.25	41.06	17.20	19.05	38.16	5.20	15.85
	new	100	0.23	0.76	63.80	26.08	0.94	2.60	4.18	1.25	6.80	17.78	1.37	3.00	0.99
		500	0.26	1.15	31.80	23.30	0.89	3.20	6.42	6.89	6.80	14.27	6.74	4.00	1.67
		1000	0.22	2.64	39.80	24.47	0.89	3.00	4.40	13.18	10.80	15.73	12.66	4.20	2.14
		3000	0.25	8.75	32.20	25.08	0.90	3.80	7.13	40.25	19.80	14.93	36.87	4.00	1.77

Cutting Plane Method + MIP: Setup

- **Instances:** Perturbed Multidimensional Knapsack
- **x Variables:** Binary
- **Software:** Python, Gurobi, Cython
- **Time:** 2 hours

Cutting Plane Method + MIP: Results

Instances			MD-VIs				
(n, m)	Gen.	$ S $	MIP	ADM	C-Wise	Mixing-set	Quantile
mk-20-10	lit	100	9.28s	7.47s	4.31s	6.34s	5.49s
		500	110.42s	46.33s	21.53s	60.40s	39.13s
		1000	642.60s	111.55s	120.40s	260.68s	164.71s
		3000	12.03%(1)	2.19%(4)	696.69s	4.60%(4)	1500.19s
	new	100	14.43s	13.01s	8.40s	8.01s	13.11s
		500	91.75s	62.04s	70.99s	72.04s	91.51s
		1000	388.66s	254.66s	296.24s	356.02s	442.39s
		3000	41.46%(0)	32.92%(0)	33.83%(1)	37.82%(0)	52.73%(0)
mk-40-30	lit	100	10.17%(0)	9.16%(1)	8.32%(1)	11.73%(0)	12.05%(0)
		500	29.22%(0)	5.73%(2)	1.81%(4)	14.44%(0)	15.76%(0)
		1000	52.17%(0)	20.85%(0)	24.03%(0)	29.35%(0)	34.95%(0)
		3000	41.63%(0)	15.07%(0)	18.14%(0)	24.66%(0)	29.13%(0)
	new	100	19.70%(0)	22.23%(0)	18.79%(0)	21.98%(0)	19.05%(0)
		500	39.24%(0)	20.45%(0)	32.42%(0)	27.21%(0)	34.72%(0)
		1000	48.89%(0)	29.81%(0)	55.00%(0)	39.56%(0)	52.94%(0)
		3000	49.05%(0)	27.68%(0)	48.18%(0)	42.26%(0)	50.00%(0)

Conclusion

Problem: Linear Chance Constrained Stochastic Programs with Finite Support

Challenges: Non-convexity, Weak LP relaxations

State of the Art: Quantile and Mixing Set Inequalities

Concept: Disjunctive Aspect of CCSPs

Theoretical Dominance:

$$MD \subset Q = BM$$

Computational Dominance: Better performance + More robust

Some Open Questions

- Heuristics for choosing α for quantile and mixing set inequalities?
- What about the Real Mixing Closure \mathcal{M} ?
- Where does \mathcal{M} stand in $\mathcal{MD} \subset \mathcal{Q} = \mathcal{BM}$?
- How close is \mathcal{MD} to $\text{conv}(F)$?
- Do stronger valid inequalities exist?

Thank You!