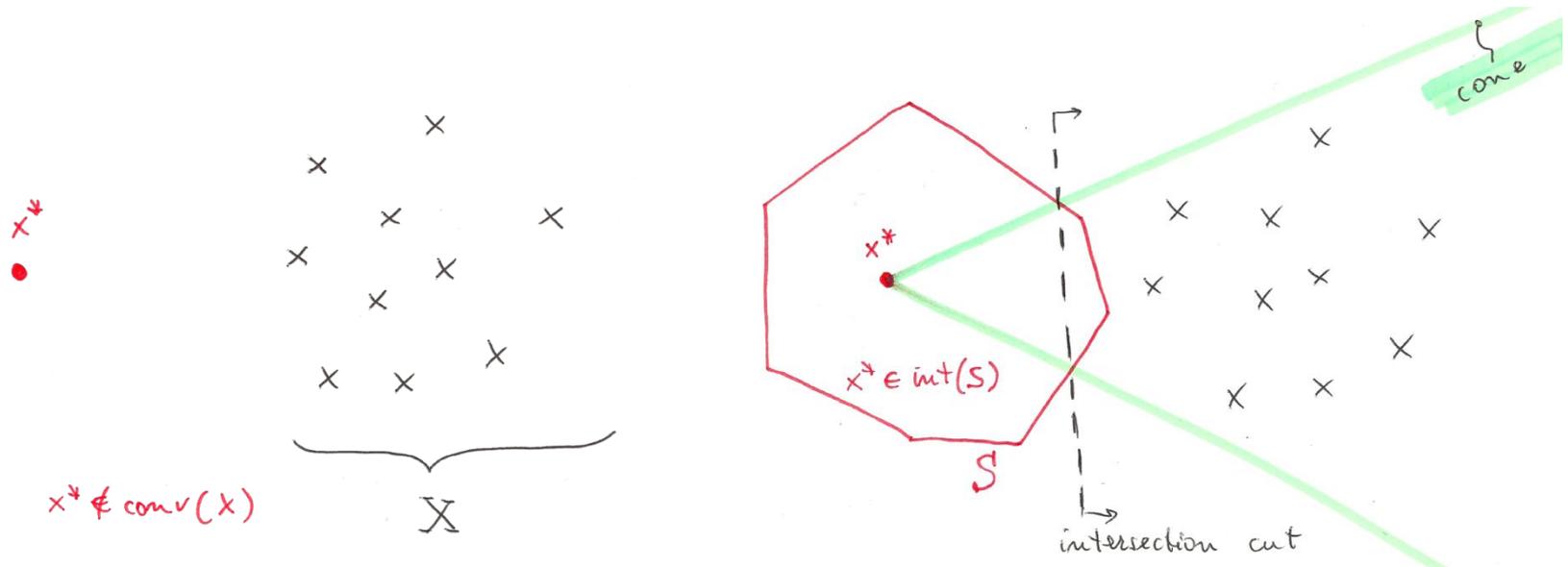


# Intersection Cuts (ICs)

- **Intersection cuts** (Balas, 1971): a powerful tool to separate, by a linear cut, a point  $\mathbf{x}^*$  from a set  $\mathbf{X}$



- All you need is (love, but also)
  - a **cone** pointed at  $\mathbf{x}^*$  containing all  $\mathbf{x} \in \mathbf{X}$
  - a **convex set  $\mathbf{S}$**  with  $\mathbf{x}^*$  (but no  $\mathbf{x} \in \mathbf{X}$ ) in its strict interior

# Branch or Cut?

## Observations:

- If  $x^*$  **vertex** of an LP relaxation, a suitable cone comes for free from the **LP basis**
- Given an infeasible point  $x^*$ , any **branching** (linear) disjunction violated by  $x^*$  implicitly defines a **convex set  $S$**  with  $x^*$  (but no feasible  $x$ ) in its **interior**

$$\bigvee_{i=1}^k (g_i^T x \geq g_{i0}) \quad \rightarrow \quad S = \{x : g_i^T x \leq g_{0i}, \quad i = 1, \dots, k\}$$

- Thus, **in principle**, one could always generate an IC instead of branching  $\rightarrow$  not always advisable because of numerical issues, slow convergence, tailing off, cut saturation, etc.

# IC separation issues

- IC separation can be problematic, as we need to read the cone rays from the LP tableau → **numerical accuracy** can be a big issue here!
- **Notation:** consider w.l.o.g. an LP in standard form (no var. ub's) and let
  - $\min\{\hat{c}^T \xi : \hat{A}\xi = \hat{b}, \xi \geq 0\}$  be the LP relaxation at a given node
  - $S = \{\xi : g_i^T \xi \leq g_{0i}, i = 1, \dots, k\}$  be a given bilinear-free set
  - $\bigvee_{i=1}^k (g_i^T \xi \geq g_{i0})$  be the disjunction to be satisfied by all feas. sol.s

# Numerically safe ICs

A **single** valid inequality can be obtained by taking, for each variable, the worst LHS Coefficient (and RHS) in each disjunction

Better applied to a normalized **reduced form** of each disjunction where the coeff. of all basic var.s is zero (kind of LP reduced costs)

$$\bigvee_{i=1}^k (g_i^T \xi \geq g_{i0})$$

$$\bigvee_{i=1}^k (\bar{g}_i^T \xi \geq \bar{g}_{i0})$$

$$\bigvee_{i=1}^k \left( \frac{\bar{g}_i^T}{\bar{g}_{i0}} \xi \geq 1 \right)$$

---

**Algorithm 1:** Intersection cut separation

---

**Input** : An LP vertex  $\xi^*$  along with its associated LP basis  $\hat{B}$ ;

the feasible-free polyhedron  $S = \{\xi : g_i^T \xi \leq g_{i0}, i = 1, \dots, k\}$  and the associated valid disjunction  $\bigvee_{i=1}^k (g_i^T \xi \geq g_{i0})$  whose members are violated by  $\xi^*$ ;

**Output:** A valid intersection cut violated by  $\xi^*$ ;

```
1 for  $i := 1$  to  $k$  do
2   |  $(\bar{g}_i^T, \bar{g}_{i0}) := (g_i^T, g_{i0}) - u_i^T(\hat{A}, \hat{b})$ , where  $u_i^T = (g_i)^T \hat{B}^{-1}$ 
3 end
4 for  $j := 1$  to  $n$  do  $\gamma_j := \max\{\bar{g}_{ij}/\bar{g}_{i0} : i \in \{1, \dots, k\}\}$ ;
5 return the violated cut  $\gamma^T \xi \geq 1$ 
```

---

# Bilevel Optimization

- The general **Bilevel Optimization Problem** (optimistic version) reads:

$$\begin{aligned} \min_{x \in \mathbb{R}^{n_1}, y \in \mathbb{R}^{n_2}} \quad & F(x, y) \\ & G(x, y) \leq 0 \\ & y \in \arg \min_{y' \in \mathbb{R}^{n_2}} \{ f(x, y') : g(x, y') \leq 0 \}. \end{aligned}$$

where  $x$  var.s only are controlled by the **leader**, while  $y$  var.s are computed by another player (the **follower**) solving a different problem.

- A very very hard problem even in a **convex setting with continuous var.s** only
- Convergent** solution algorithms are problematic and typically require additional assumptions (binary/integer var.s or alike)

# Reformulation

$$\min_{x \in \mathbb{R}^{n_1}, y \in \mathbb{R}^{n_2}} F(x, y)$$

$$G(x, y) \leq 0$$

$$y \in \arg \min_{y' \in \mathbb{R}^{n_2}} \{f(x, y') : g(x, y') \leq 0\}.$$

- By defining the **value function**

$$\Phi(x) = \min_{y \in \mathbb{R}^{n_2}} \{f(x, y) : g(x, y) \leq 0\},$$

the problem can be restated as

$$\min F(x, y)$$

$$G(x, y) \leq 0$$

$$g(x, y) \leq 0$$

$$f(x, y) \leq \Phi(x)$$

$$(x, y) \in \mathbb{R}^n.$$

- Dropping the nonconvex condition  $f(x, y) \leq \Phi(x)$  one gets the so-called **High Point Relaxation** (HPR)

# Mixed-Integer Bilevel Linear Problems

- We will focus the **Mixed-Integer Bilevel Linear** case (MIBLP)

$$\begin{aligned} \min & F(x, y) \\ & G(x, y) \leq 0 \\ & g(x, y) \leq 0 \\ & (x, y) \in \mathbb{R}^n \\ & f(x, y) \leq \Phi(x) \\ & x_j \text{ integer, } \forall j \in J_1 \\ & y_j \text{ integer, } \forall j \in J_2, \end{aligned}$$

where  $F$ ,  $G$ ,  $f$  and  $g$  are **linear** (actually, affine) **functions**

- Note that  $f(x, y) \leq \Phi(x)$  is **nonconvex** even when all  $y$  var.s are continuous

# MIBLP statement

- Using standard LP notation, our MIBLP reads

$$\begin{aligned} \min_{x,y} \quad & c_x^T x + c_y^T y \\ & G_x x + G_y y \leq q \\ & Ax + By \leq b \\ & l \leq y \leq u \\ & x_j \text{ integer, } \forall j \in J_x \\ & y_j \text{ integer, } \forall j \in J_y \\ & d^T y \leq \Phi(x) \end{aligned}$$

where for a given  $x = x^*$  one computes the value function by solving the following MILP:

$$\Phi(x^*) := \min_{y \in \mathbb{R}^{n_2}} \{d^T y : By \leq b - Ax^*, \quad l \leq y \leq u, \quad y_j \text{ integer } \forall j \in J_y\}.$$

# Example

- A notorious example from J. Moore and J. Bard. The mixed integer linear bilevel programming problem. *Operations Research*, 38(5):911–921, 1990.

$$\min_{x \in \mathbb{Z}} -x - 10y$$

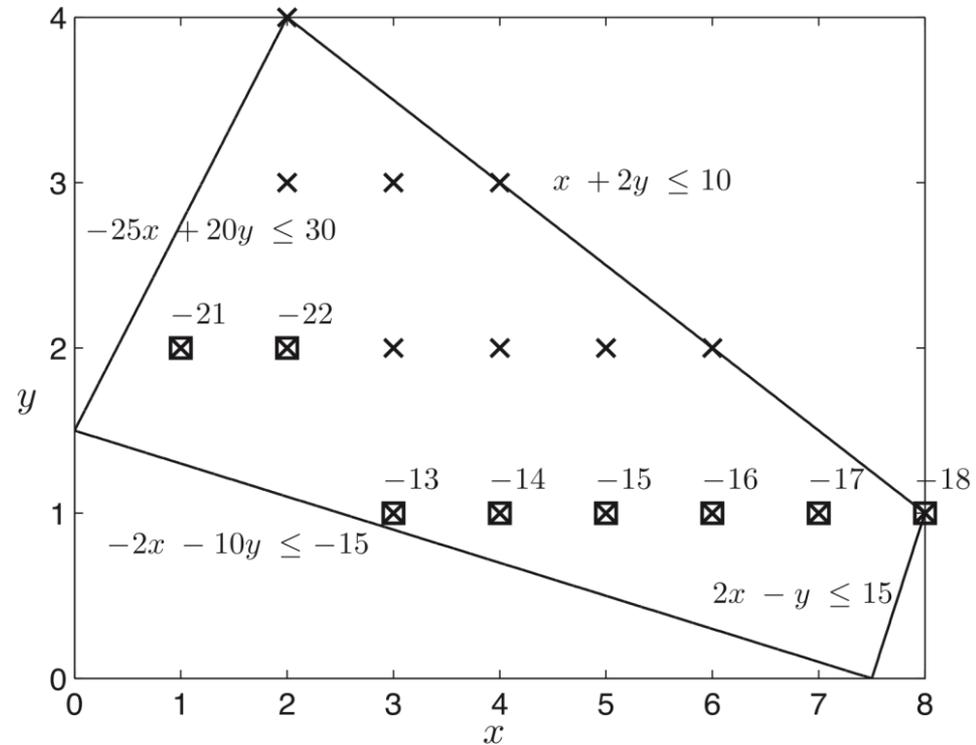
$$y \in \arg \min_{y' \in \mathbb{Z}} \{ y' :$$

$$-25x + 20y' \leq 30$$

$$x + 2y' \leq 10$$

$$2x - y' \leq 15$$

$$2x + 10y' \geq 15 \}$$



where  $f(x, y) = y$

**x** points of HPR relax.

\_\_\_\_\_ LP relax. of HPR

# Example (cont.d)

Value-function reformulation

$$\min -x - 10y$$

$$-25x + 20y \leq 30$$

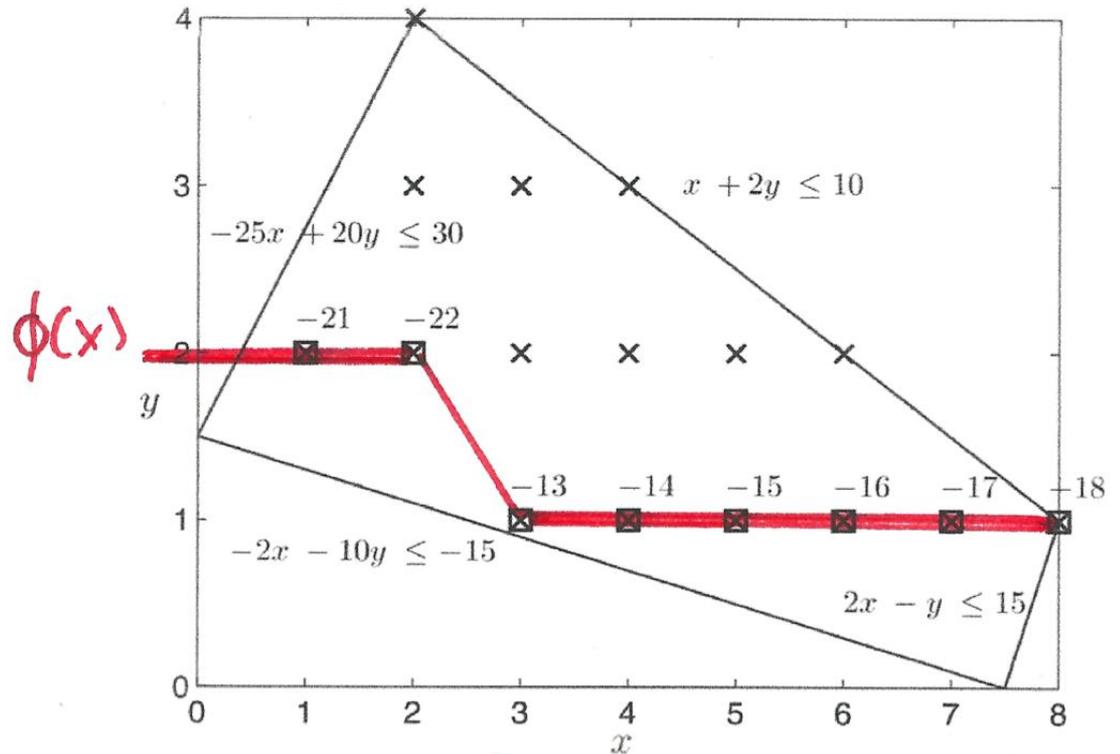
$$x + 2y \leq 10$$

$$2x - y \leq 15$$

$$-2x - 10y \leq -15$$

$$x, y \in \mathbb{Z}$$

$$y \leq \Phi(x)$$



# A MILP-based B&C solver

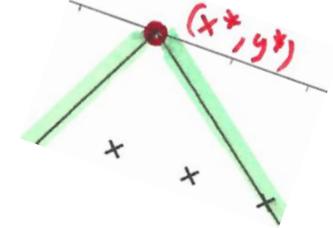
- Suppose you want to apply a **Branch-and-Cut** MILP solver to HPR
- Forget for a moment about internal heuristics (i.e., deactivate all of them), and assume the LP relaxation at each node is solved by the simplex algorithm
- **What do we need to add to the MILP solver to handle a MIBLP?**
- At each node, let  $(\mathbf{x}^*, \mathbf{y}^*)$  be the current **LP optimal vertex**:

*if  $(\mathbf{x}^*, \mathbf{y}^*)$  is fractional  $\rightarrow$  branch as usual*

*if  $(\mathbf{x}^*, \mathbf{y}^*)$  is integer and  $f(x^*, y^*) \leq \Phi(x^*) \rightarrow$  update the incumbent as usual*

# The difficult case

- But, what can we do in third possible case, namely  $(x^*, y^*)$  is integer but **not bilevel-feasible**, i.e., when  $f(x^*, y^*) > \Phi(x^*)$ ?



- **Question: how can we cut this integer  $(x^*, y^*)$  ?**

Possible answers from the literature

- If  $(x, y)$  is restricted to be **binary**, add a **no-good cut** requiring to flip at least one variable w.r.t.  $(x^*, y^*)$  or w.r.t.  $x^*$
- If  $(x, y)$  is restricted to be **integer** and all MILP coeff.s are integer, add a cut requiring a slack of 1 for the sum of all the inequalities that are tight at  $(x^*, y^*)$
- Are weak conditions as they do not address the **reason of infeasibility** by trying to enforce  $f(x^*, y^*) \leq \Phi(x^*)$  somehow

# Use Intersection Cuts!

- Our idea is first illustrated on the Moore&Bard example

$$\min_{x \in \mathbb{Z}} -x - 10y$$

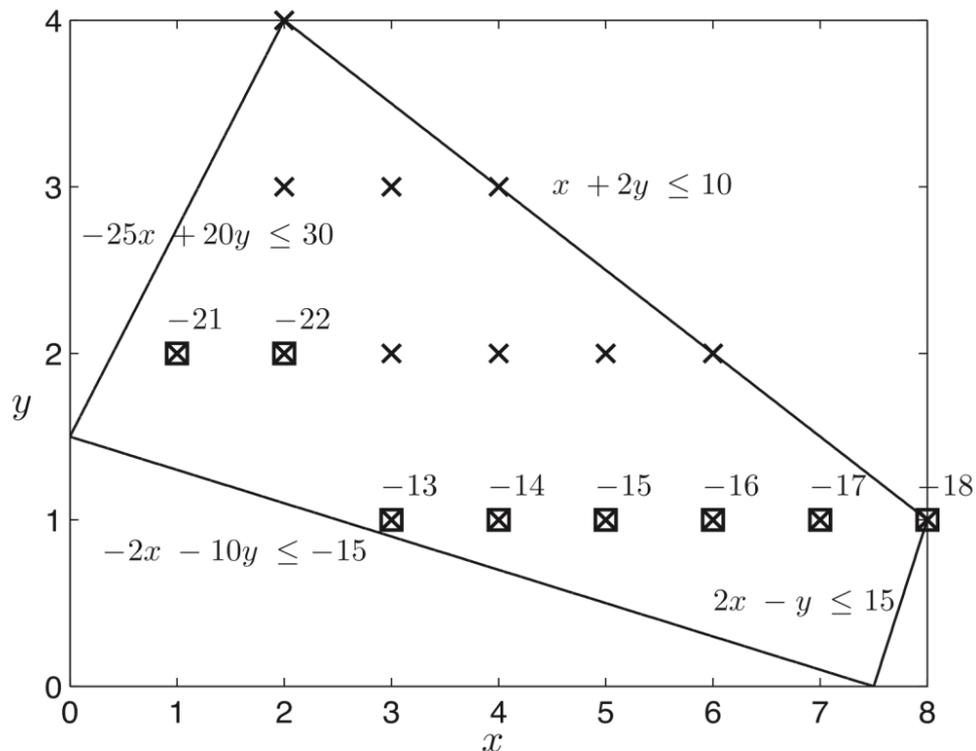
$$y \in \arg \min_{y' \in \mathbb{Z}} \{ y' :$$

$$\begin{aligned} -25x + 20y' &\leq 30 \\ x + 2y' &\leq 10 \\ 2x - y' &\leq 15 \\ 2x + 10y' &\geq 15 \end{aligned} \}$$

where  $f(x,y) = y$

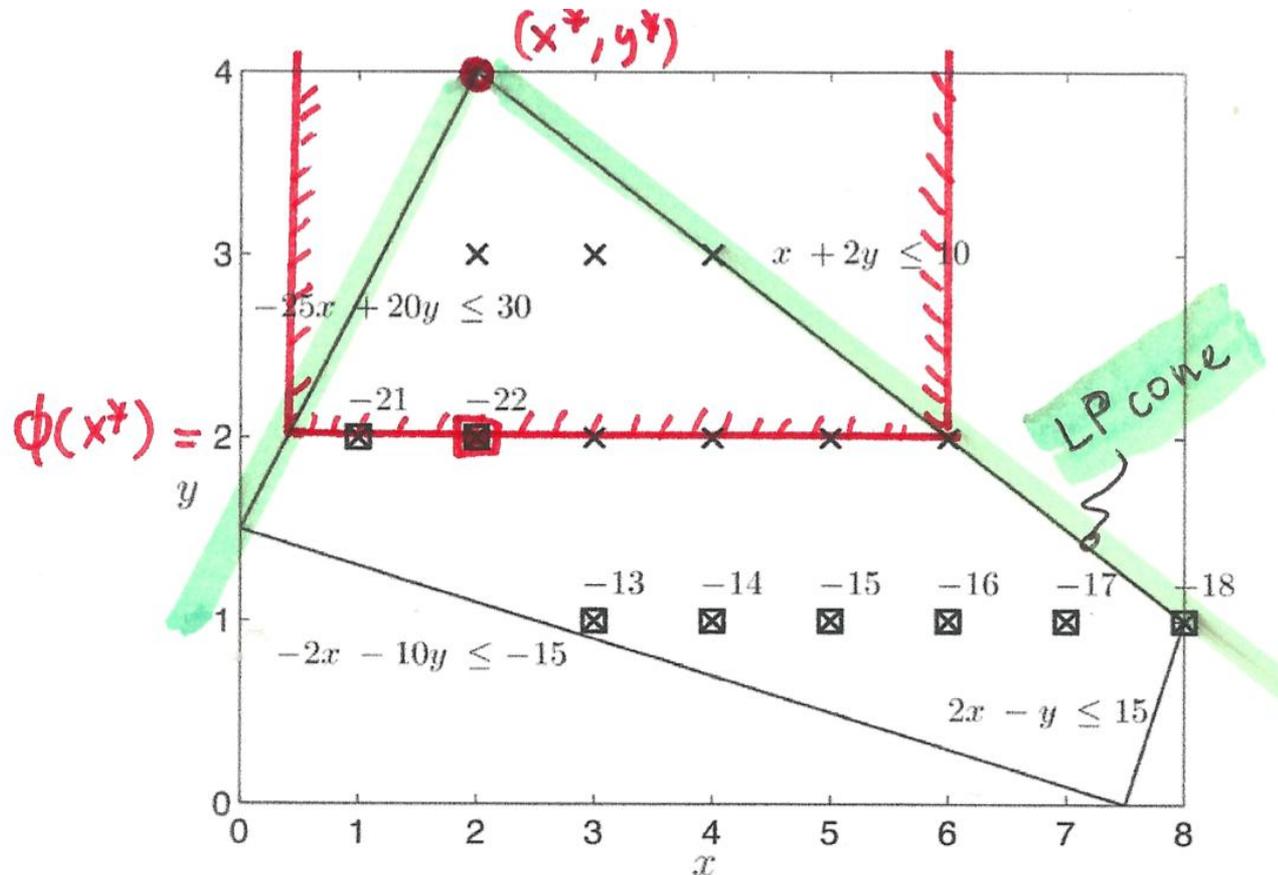
**x** points of HPR relax.

\_\_\_\_\_ LP relax. of HPR



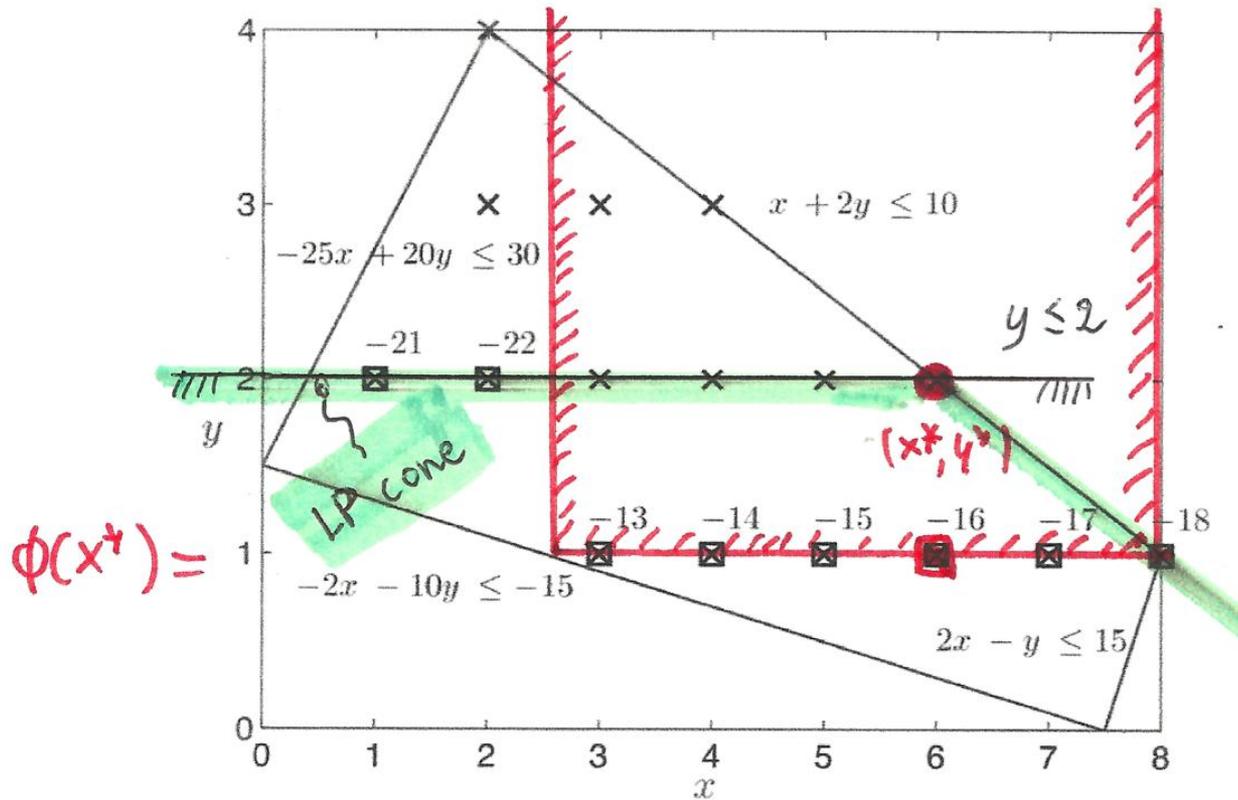
# Define a suitable bilevel-free set

- Take the LP vertex  $(x^*, y^*) = (2, 4) \rightarrow f(x^*, y^*) = y^* = 4 > \Phi(x^*) = 2$



# Intersection cut

- We can therefore generate the intersection cut  $y \leq 2$  and repeat



# A basic bilevel-free set

**Lemma 1.** *For any feasible solution  $\hat{y}$  of the follower, the set*

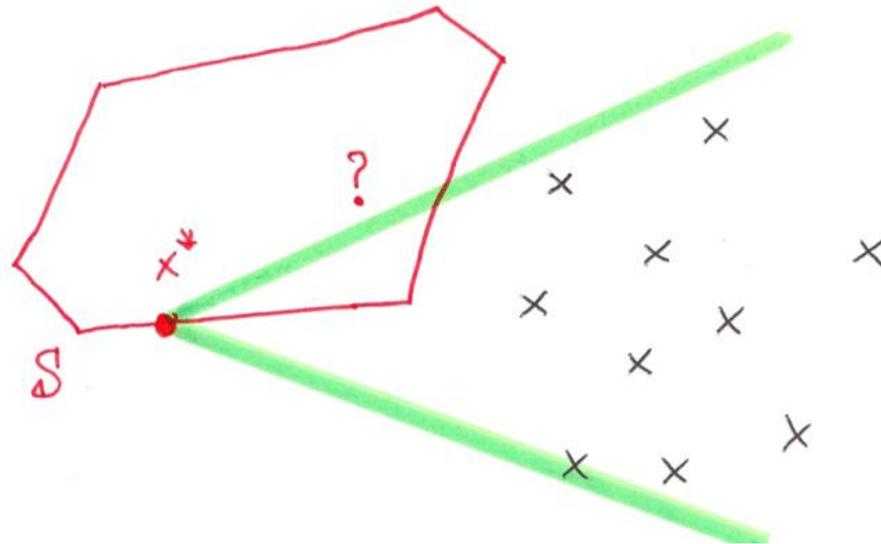
$$S(\hat{y}) = \{(x, y) \in \mathbb{R}^n : f(x, y) \geq f(x, \hat{y}), g(x, \hat{y}) \leq 0\} \quad (10)$$

*does not contain any bilevel-feasible point in its interior.*

- **Note:**  $S(\hat{y})$  is a convex set (actually, a **polyhedron**) when  $f$  and  $g$  are affine functions, i.e., in the MIBLP case
- **Separation algorithm:** given an optimal vertex  $(x^*, y^*)$  of the LP relaxation of HPR
  - Solve the follower for  $x=x^*$  and get an optimal sol., say  $\hat{y}$
  - **if**  $(x^*, y^*)$  strictly inside  $S(\hat{y})$  **then**
    - generate a violated IC using the LP-cone pointed at  $(x^*, y^*)$  together with the bilevel-free set  $S(\hat{y})$

# A technical issue...

- However, the above does not lead to a proper MILP algorithm as a **bilevel-infeasible** integer vertex  $(x^*, y^*)$  can be on the **frontier** of the bilevel-free set  $S$ , so we cannot be sure to cut it by using our IC's



- We need to define the bilevel-free set in a **more clever way** if we want be sure to cut  $(x^*, y^*)$

# An enlarged bilevel-free set

- Assuming  $g(x,y)$  is integer for all integer HPR solutions, one can “move apart” the frontier of  $S(\hat{y})$  so as to be sure that vertex  $(x^*,y^*)$  belongs to its interior

**Theorem 1.** *Assume that  $g(x,y)$  is integer for all HPR solutions  $(x,y)$ . Then, for any feasible solution  $\hat{y}$  of the follower, the extended set*

$$S^+(\hat{y}) = \{(x,y) \in \mathbb{R}^n : f(x,y) \geq f(x,\hat{y}), g(x,\hat{y}) \leq 1\} \quad (11)$$

*does not contain any bilevel-feasible point in its interior, where 1 denotes a vector of all one's.*

- The corresponding IC is **always violated** by  $(x^*,y^*) \rightarrow$  IC separation to be implemented in a lazy constraint/usercut callback to produce a (locally valid) violated cut  $\rightarrow$  **B&C solver for MIBLP**
- Note: **alternative bilevel-free sets** can be defined to produce hopefully deeper ICs

# Conclusions

- Mixed-Integer Bilevel Linear Programming is a **MILP** plus additional constr.s
- **Intersection cuts** can produce valuable information at the B&B nodes
- Sound MIBLP **heuristics, preprocessing** etc. (not discussed here) available
- Many instances from the literature can be **solved in a satisfactory way**
- **Binary** code available (ask Markus Sinnl for a free license)

**Slides** <http://www.dei.unipd.it/~fisch/papers/slides/>

## Reference papers:

M. Fischetti, I. Ljubic, M. Monaci, M. Sinnl, "Intersection cuts for bilevel optimization", in Integer Programming and Combinatorial Optimization: 18th International Conference, IPCO 2016 Proceedings, 77-88, *Mathematical Programming* 172(1), 77-103, 2018

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